### CMSC 473/673 Natural Language Processing

Instructor: Lara J. Martin (she/they)

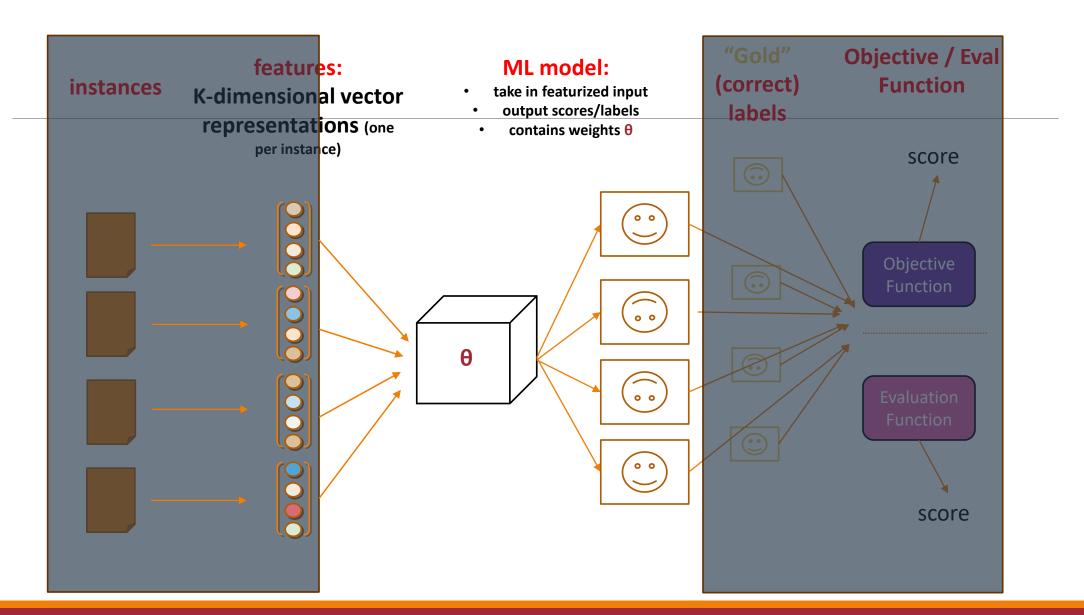
TA: Duong Ta (he)

### Learning Objectives

Define the basic cell architecture of an RNN

Backpropagate loss through an example RNN

#### Defining the Model



Review: Maxent Language Models

given some context... **W**<sub>i-3</sub>  $W_{i-2}$  $W_{i-1}$ compute beliefs about what is likely...  $p(w_i|w_{i-3}, w_{i-2}, w_{i-1}) = \text{softmax}(\theta_{w_i} \cdot f(w_{i-3}, w_{i-2}, w_{i-1}))$ can we learn word-specific weights predict the next word  $W_i$ 

(by type)?

#### Review: Neural Language Models

given some context... **W**<sub>i-3</sub>  $W_{i-2}$  $W_{i-1}$ can we *learn* the feature function(s) for *just* the context? compute beliefs about what is likely...  $p(w_i|w_{i-3}, w_{i-2}, w_{i-1}) = \text{softmax}(\theta_{w_i} \cdot f(w_{i-3}, w_{i-2}, w_{i-1}))$ can we learn word-specific weights predict the next word (by type)?  $W_i$ 

#### Review: Neural Language Models

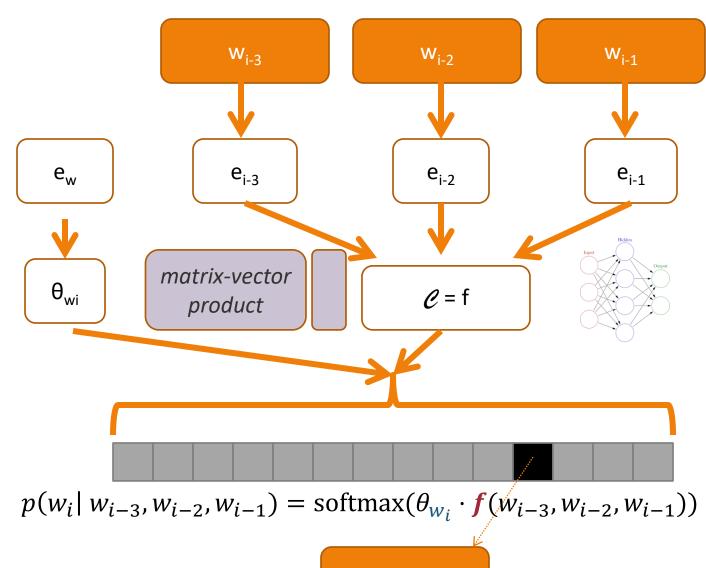
given some context...

create/use
"distributed
representations"...

combine these representations...

compute beliefs about what is likely...

predict the next word



 $W_i$ 

#### LM Comparison

**COUNT-BASED** 

**MAXENT** 

**NEURAL** 

Class-specific

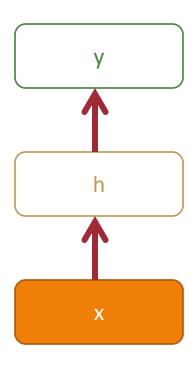
Class-based

Uses features

Class-based

Uses *embedded* features

### Network Types: Flat Input, Flat Output



#### Feed forward

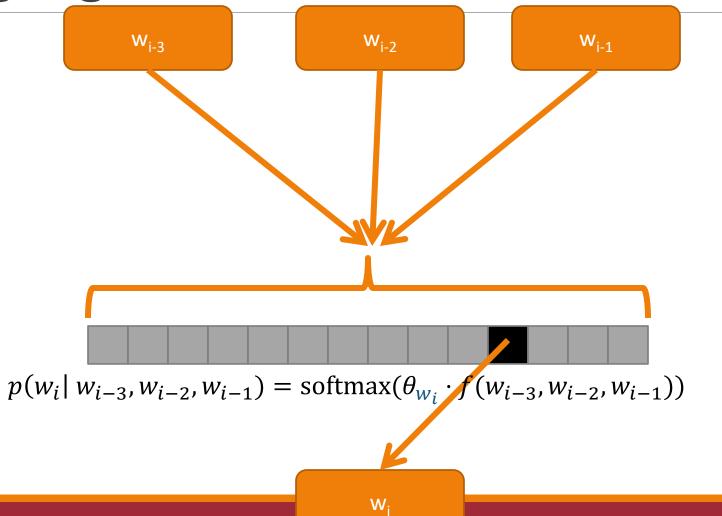
Linearizable feature input
Bag-of-items classification/regression
Basic non-linear model

Maxent Language Models

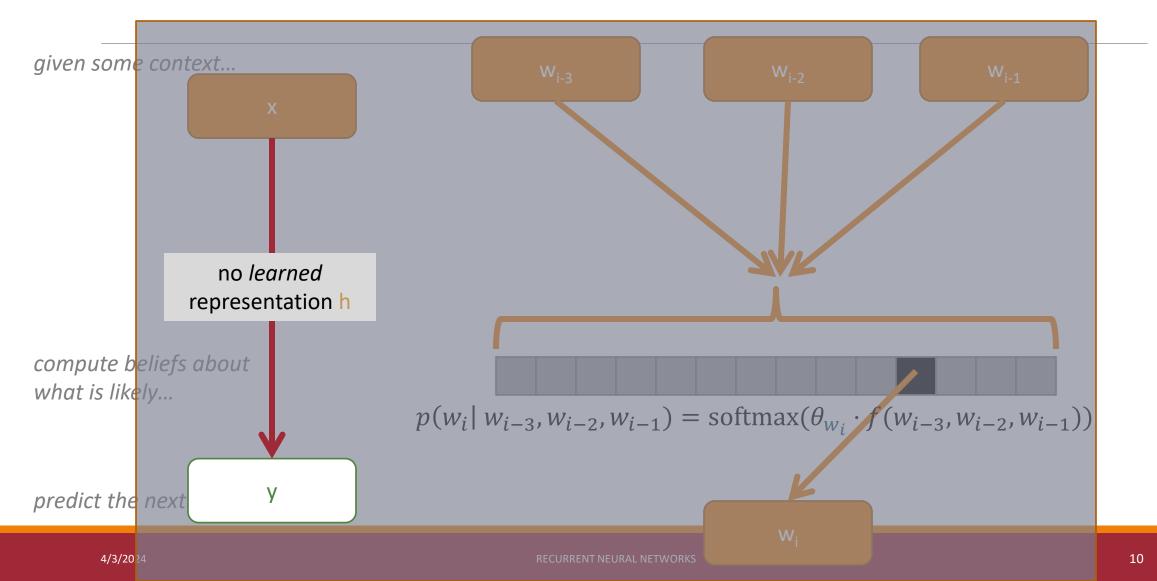
given some context...

compute beliefs about what is likely...

predict the next word



#### Maxent Language Models



### Neural Language Models

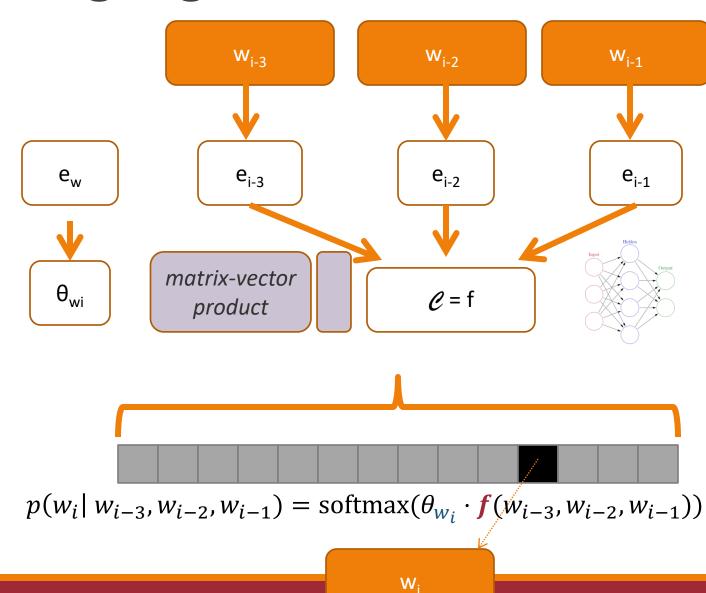
given some context...

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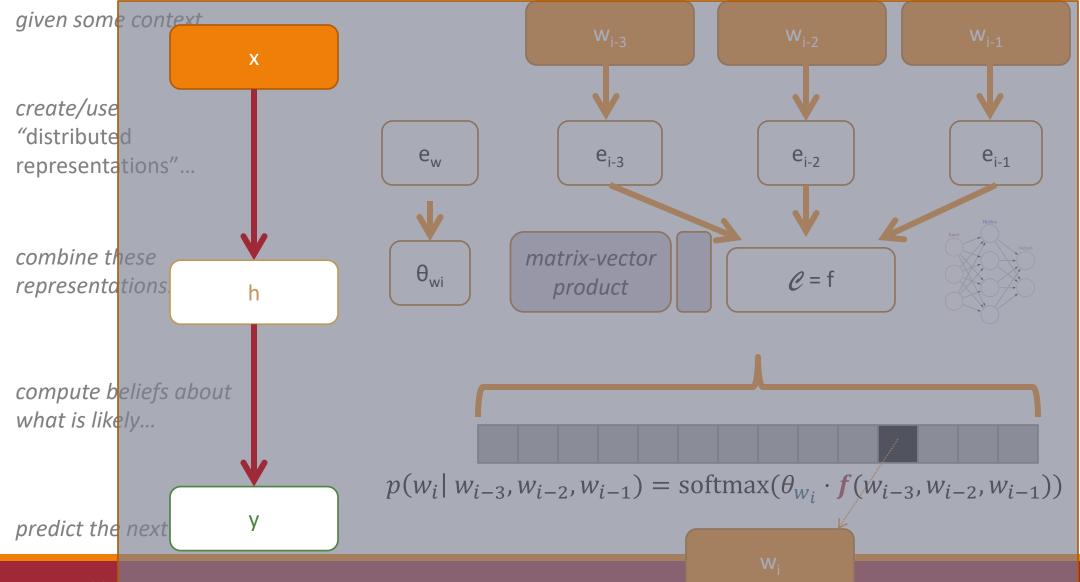
combine these representations...

compute beliefs about what is likely...

predict the next word



### Neural Language Models



# Common Types of Flat Input, Flat Output

```
Feed forward networks
```

Multilayer perceptrons (MLPs)

#### General Formulation:

```
Input: x
Compute:
```

```
h_0 = x
for layer I = 1 to L:
h_I = f_I(W_I h_{I-1} + b_I) linear layer
```

```
hidden state (non-linear) at layer I activation function at I return \mathop{\rm argmax}\limits_{\mathcal{V}} \operatorname{softmax}(\theta h_L)
```

In Pytorch (torch.nn):

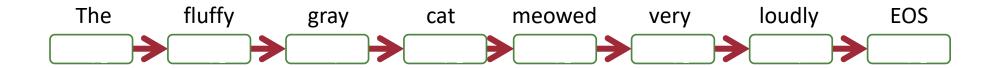
#### **Activation functions:**

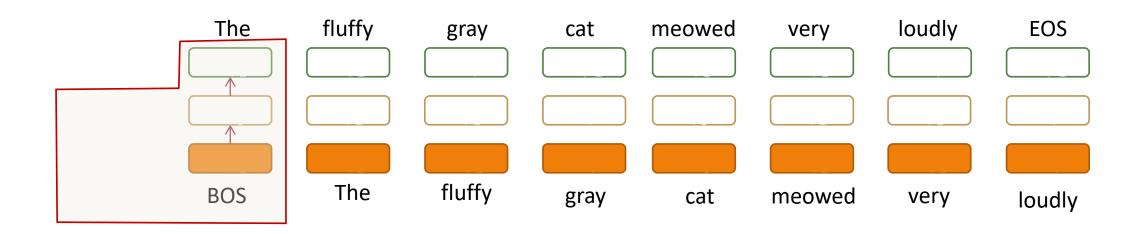
https://pytorch.org/docs/stable/nn.html?highlight
=activation#non-linear-activations-weighted-sumnonlinearity

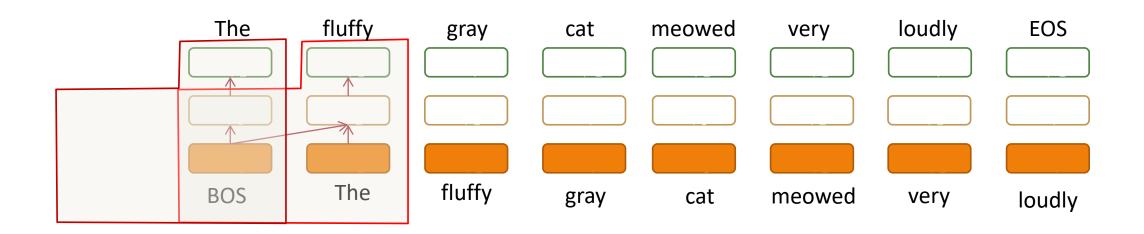
#### Linear layer:

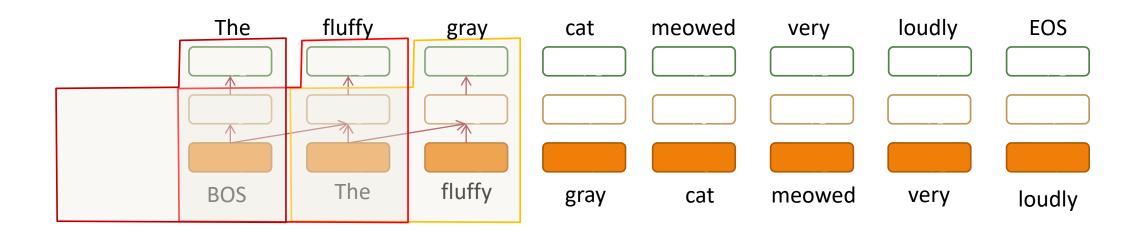
https://pytorch.org/docs/stable/nn.html#linearlayers

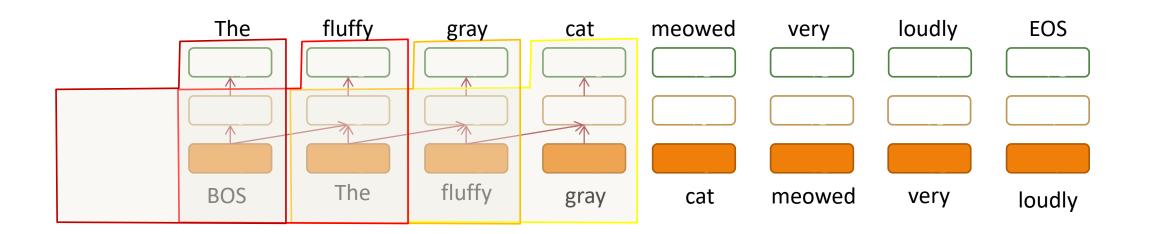
```
torch.nn.Linear(
    in_features=<dim of h<sub>l-1</sub>>,
    out_features=<dim of h<sub>l</sub>>,
    bias=<Boolean: include bias b<sub>l</sub>>)
```

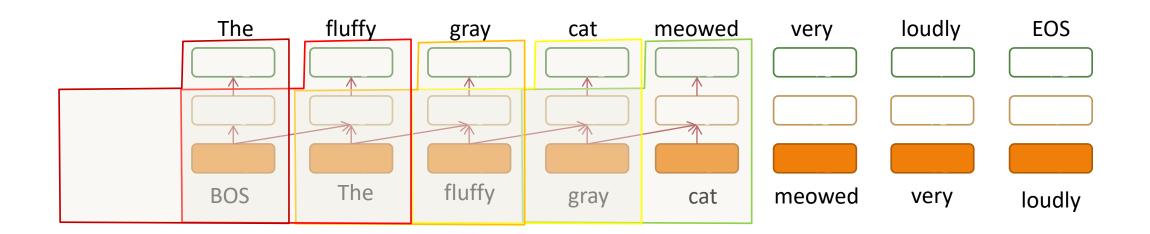


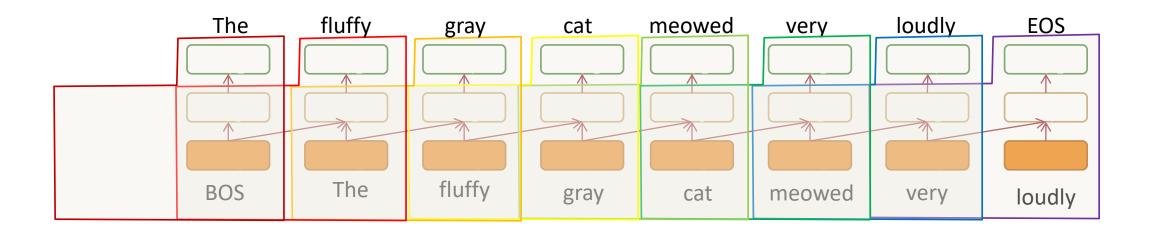






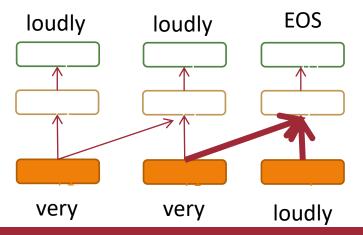






#### A Neural N-Gram Model (N=3)

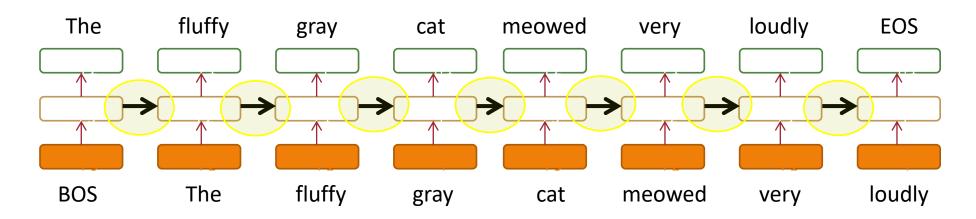
The fluffy gray cat meowed very loudly



Critical issue: the amount of information flow is fundamentally restricted!!!

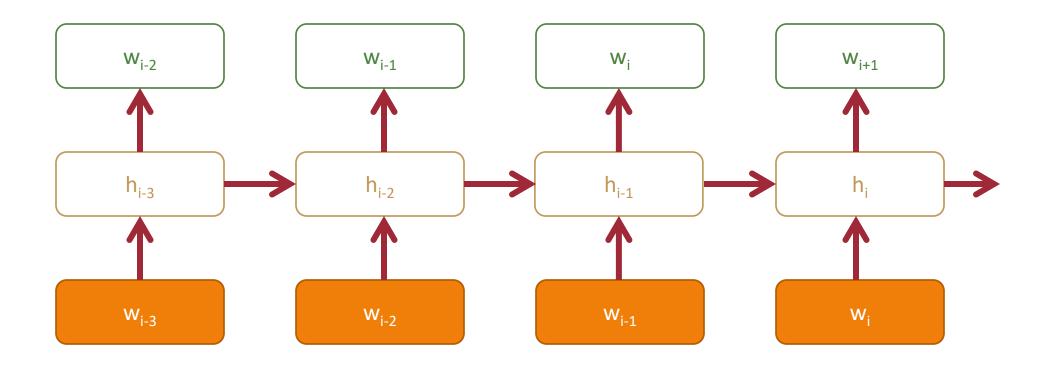
#### A Recurrent Neural Language Model

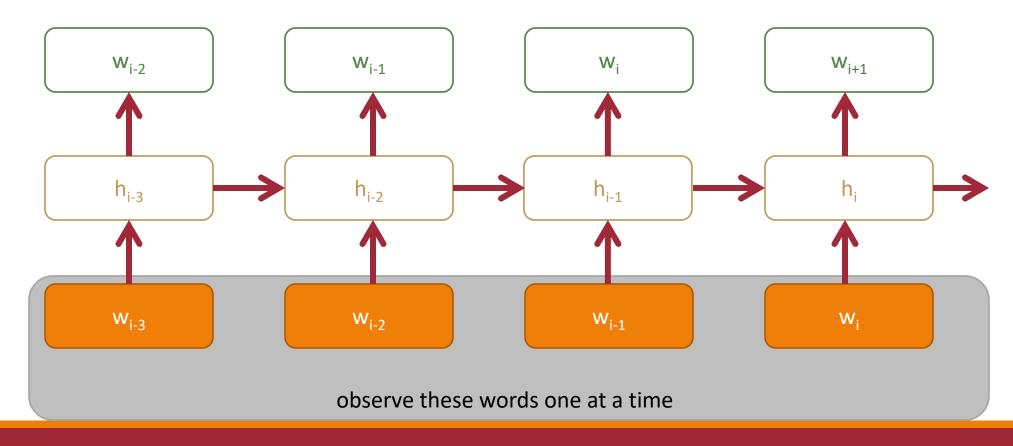
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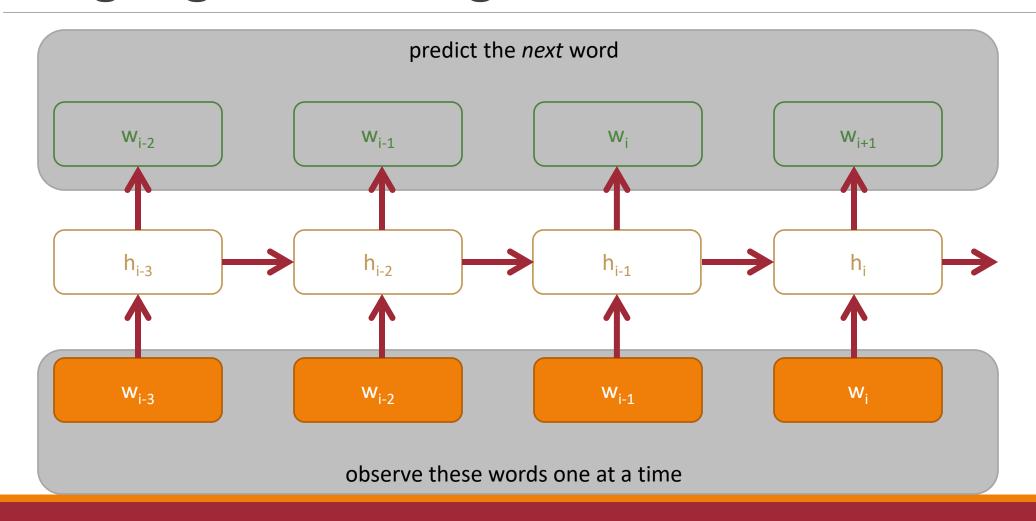


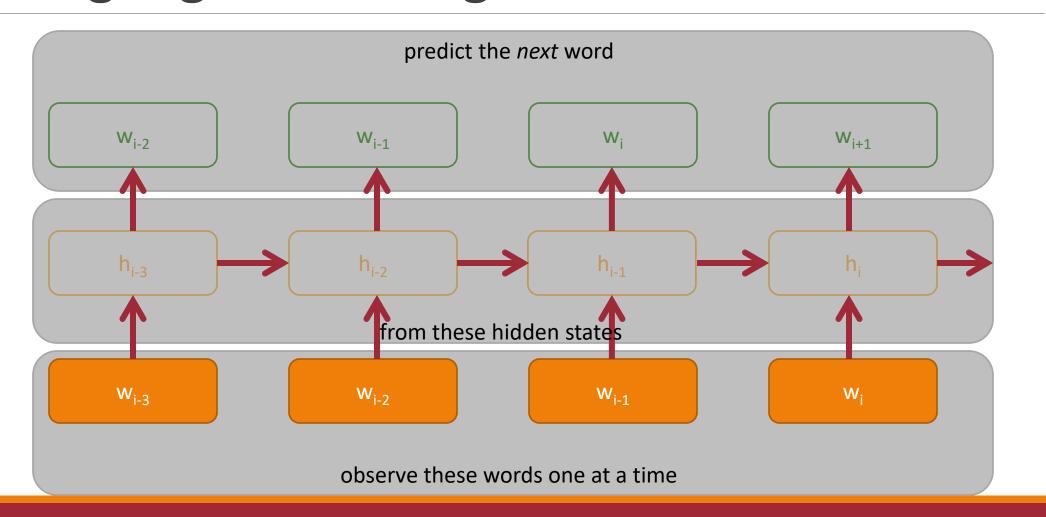
Critical issue: the amount of information flow is fundamentally restricted!!!

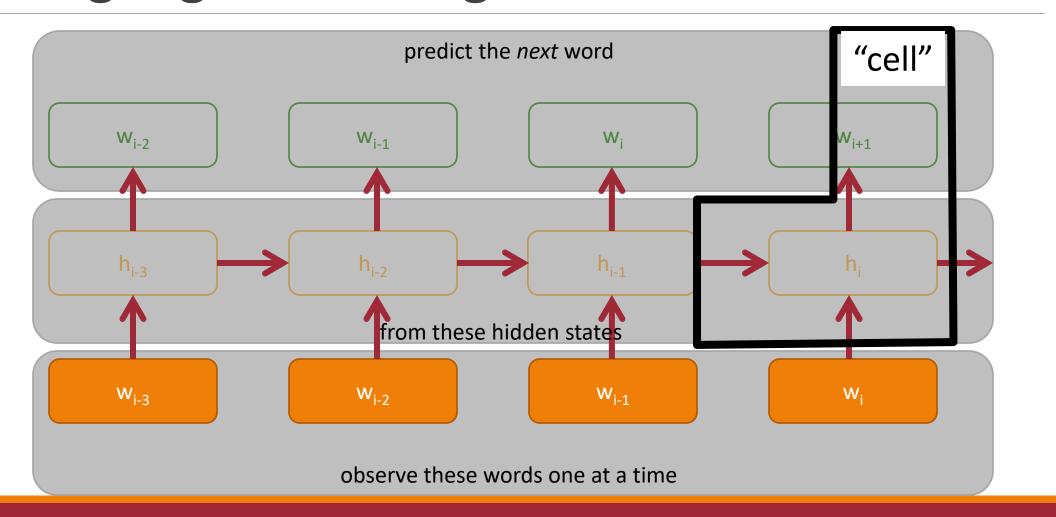
Allowing signal to flow from one hidden state to another could help solve this!

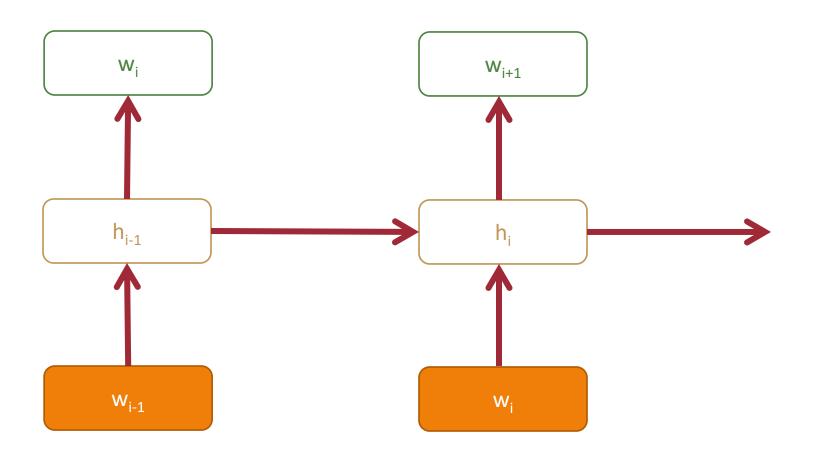


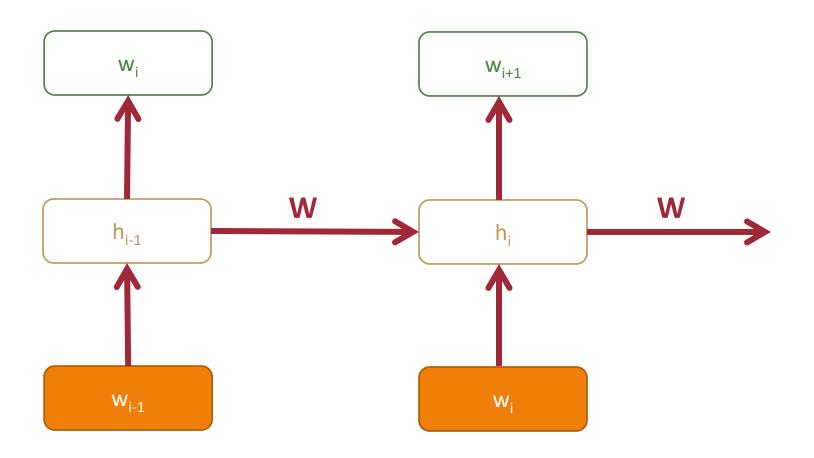


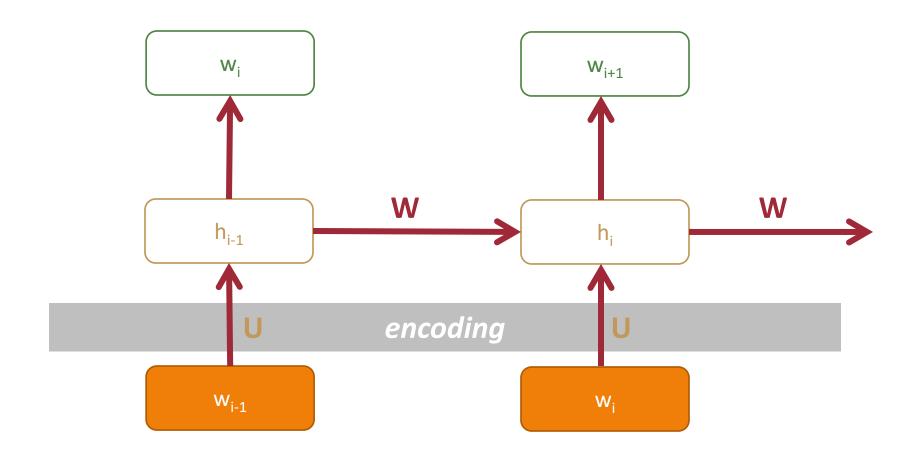


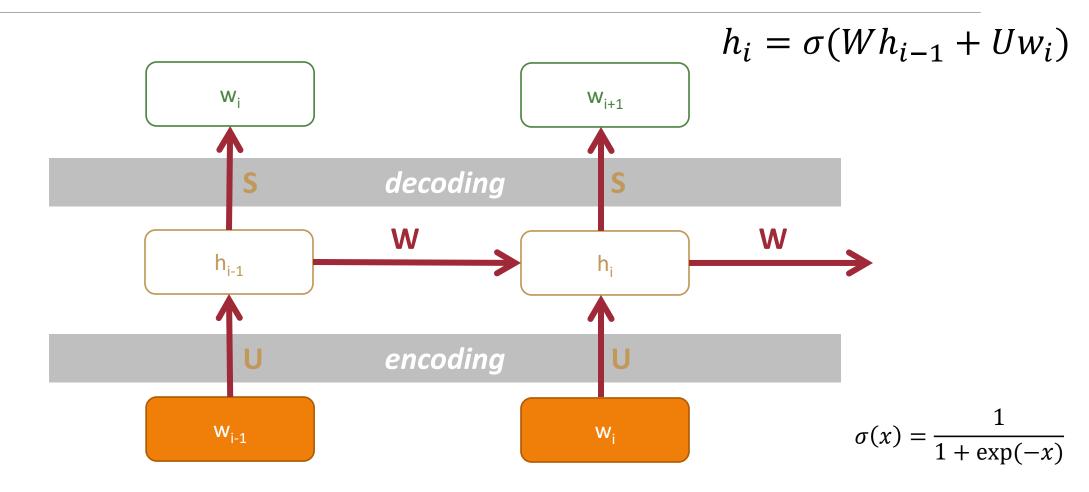


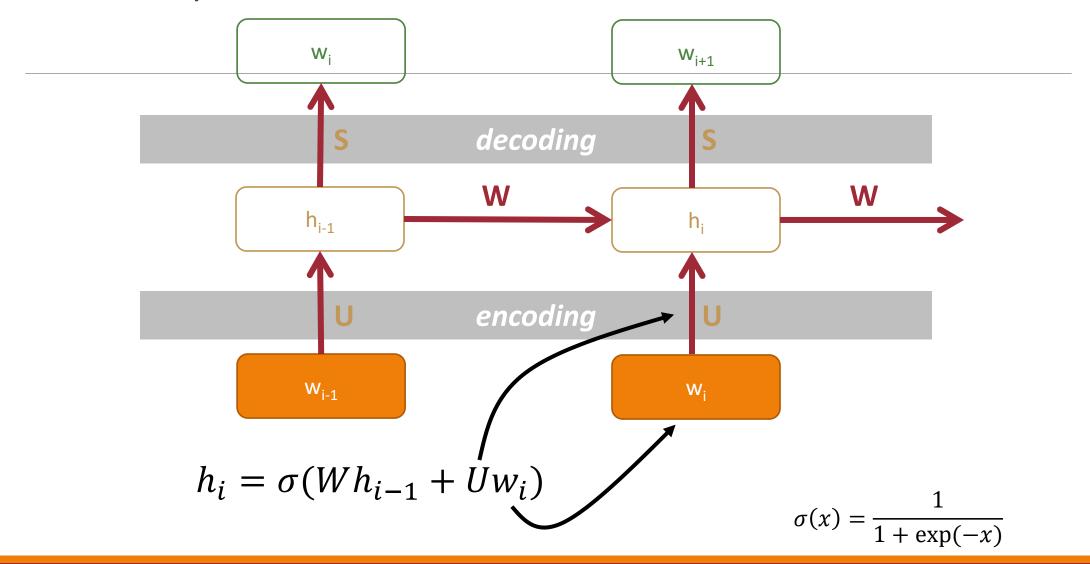


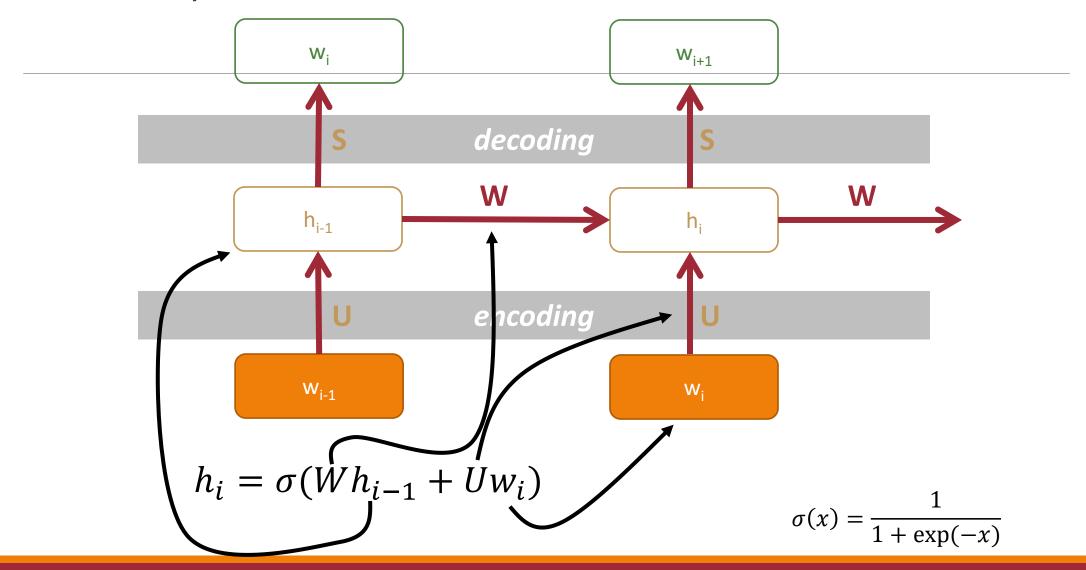


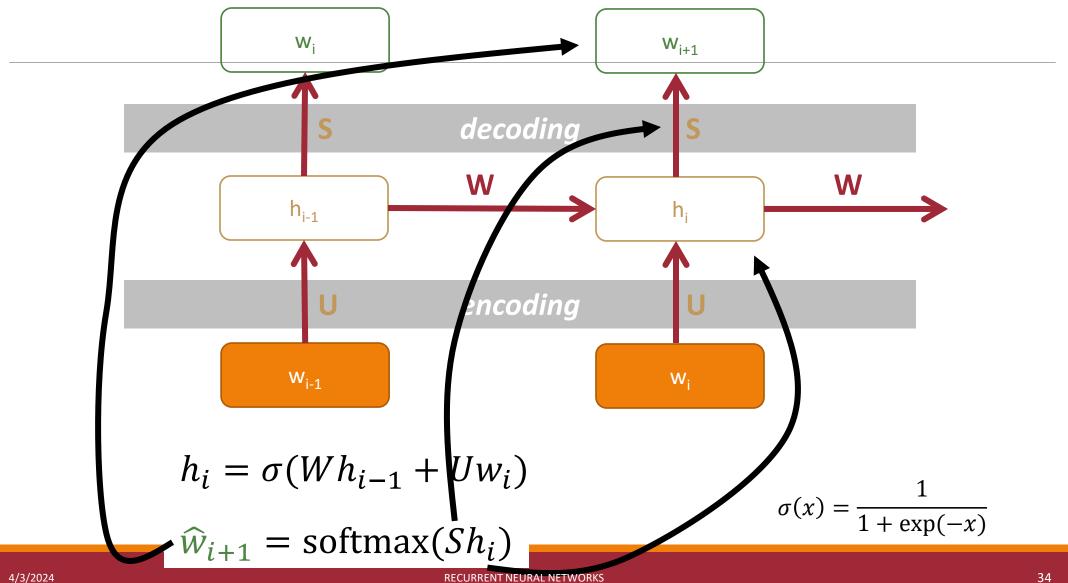


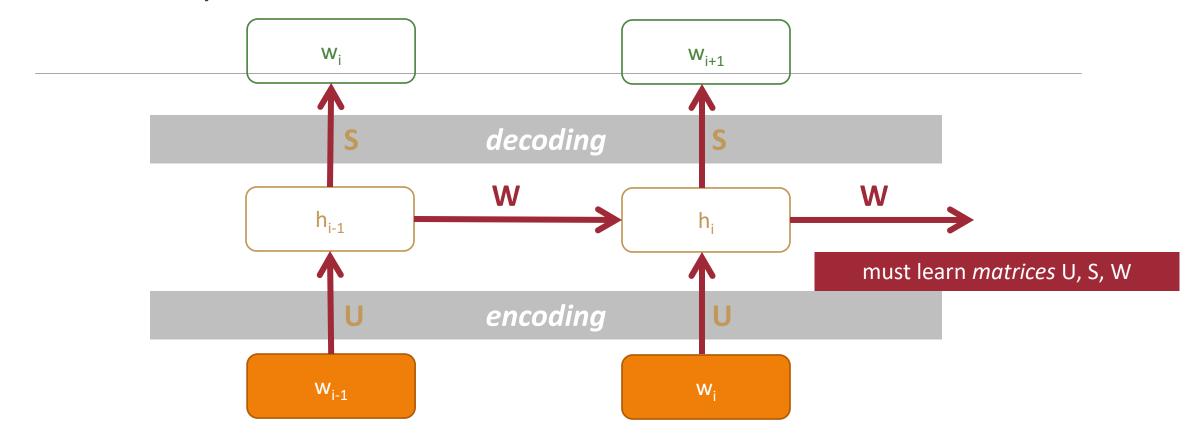






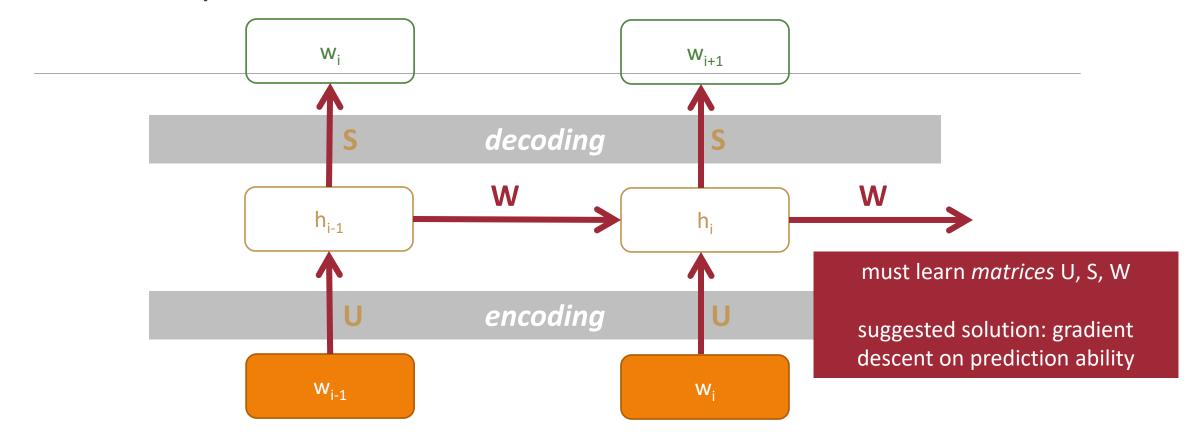






$$h_i = \sigma(Wh_{i-1} + Uw_i)$$

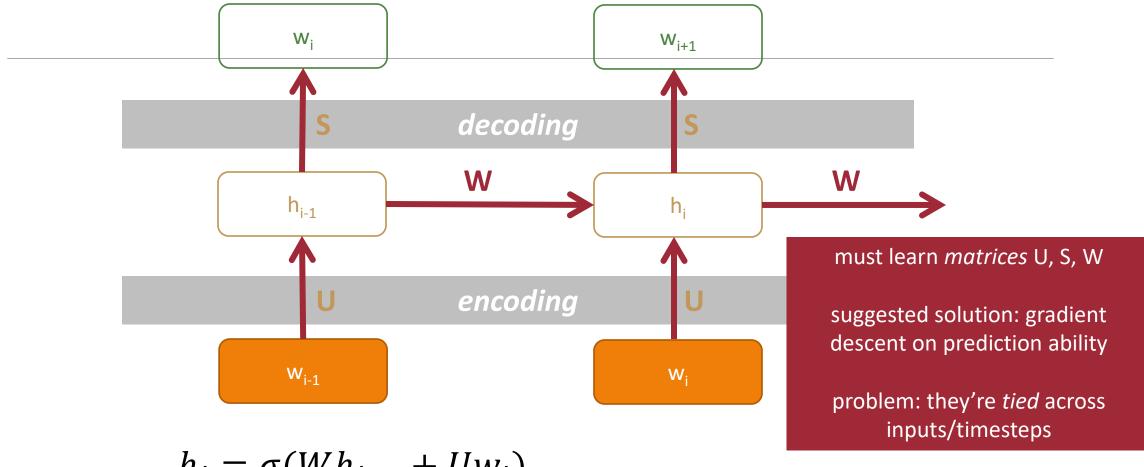
$$\widehat{w}_{i+1} = \operatorname{softmax}(Sh_i)$$



$$h_i = \sigma(Wh_{i-1} + Uw_i)$$

$$\widehat{w}_{i+1} = \operatorname{softmax}(Sh_i)$$

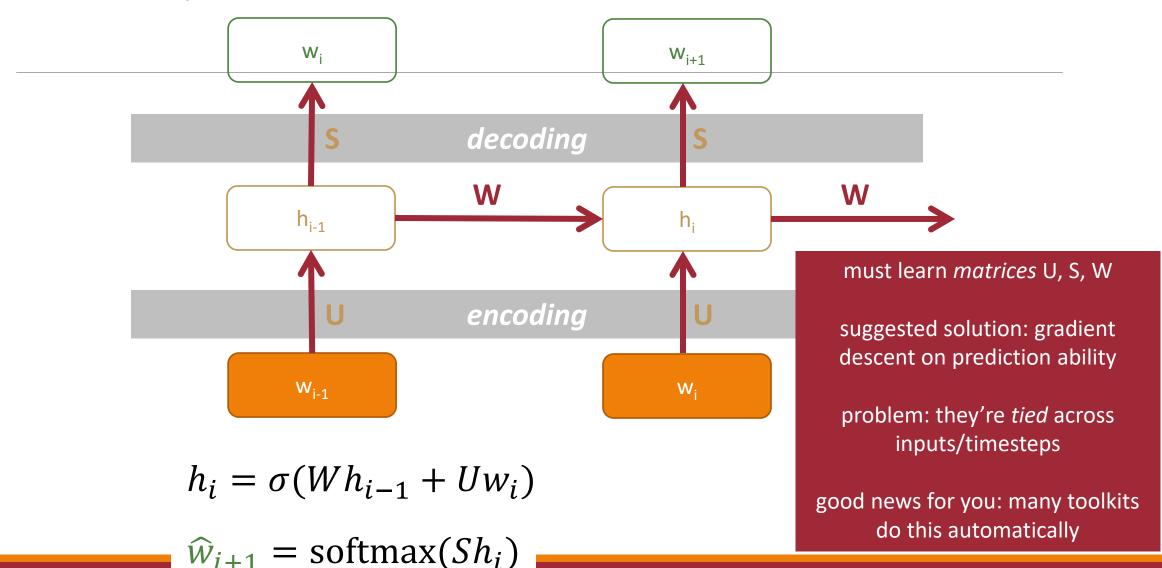
### A Simple Recurrent Neural Network Cell



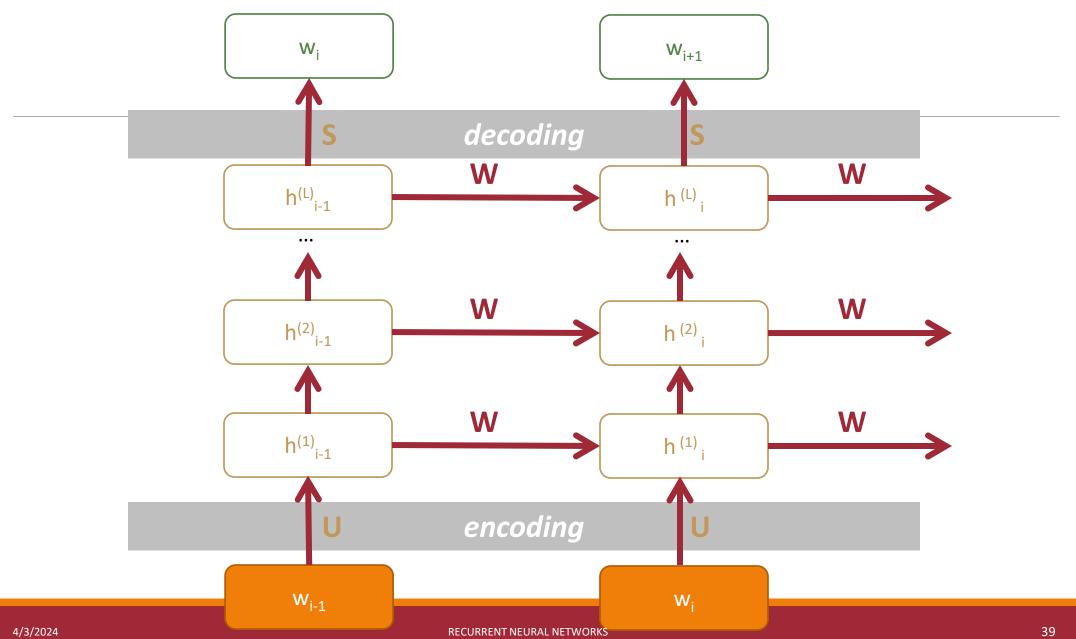
$$h_i = \sigma(Wh_{i-1} + Uw_i)$$

$$\widehat{w}_{i+1} = \operatorname{softmax}(Sh_i)$$

### A Simple Recurrent Neural Network Cell



#### A Multi-Layer Simple Recurrent Neural Network Cell



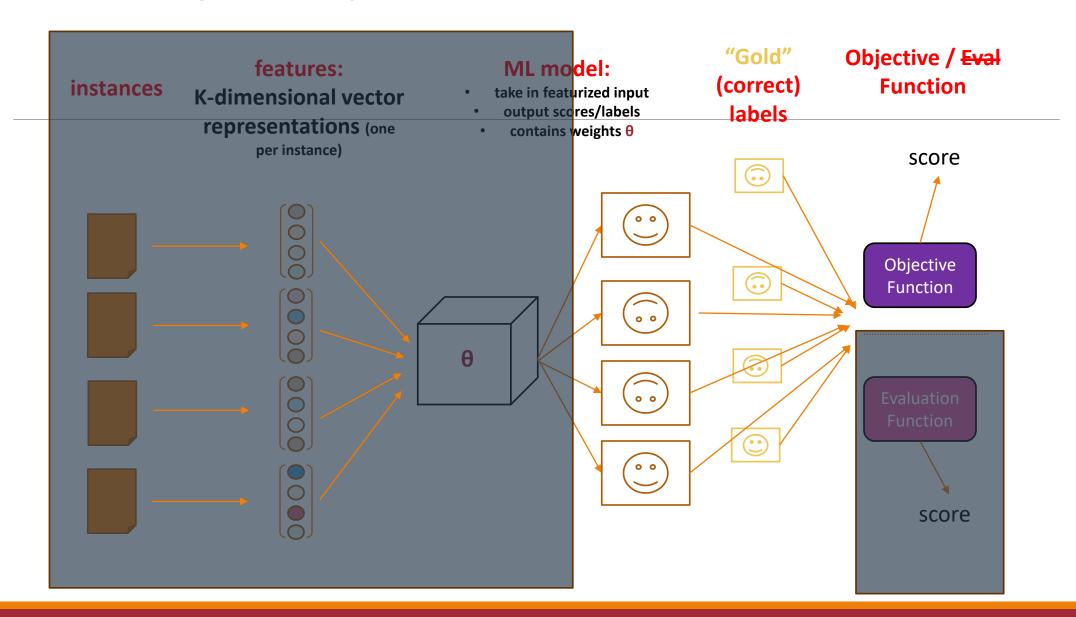
## How do you learn an RNN?

As with other approaches: Compute the loss and perform gradient descent

Loss: Cross-entropy, computed per output word

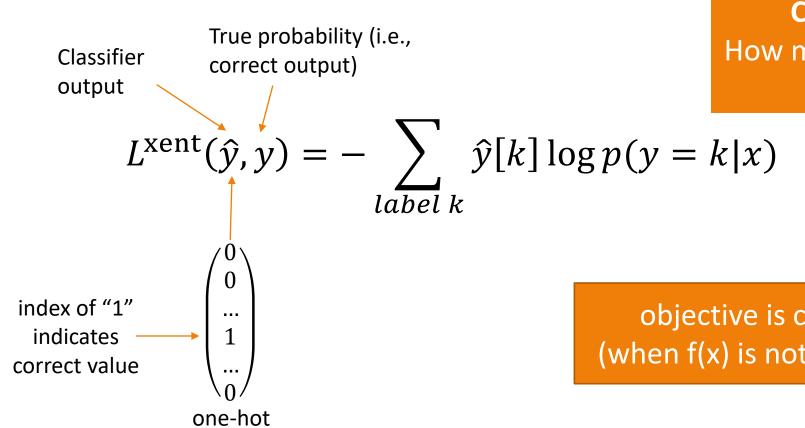
• Just as with prior LM approaches!

### Defining the Objective



## Review: Minimize Cross Entropy Loss

vector



**Cross entropy:** 

How much  $\hat{y}$  differs from the true y

objective is convex (when f(x) is not learned)

# Gradient Descent: Backpropagate the Error

Initialize model

Set t = 0

Pick a starting value  $\theta_t$ 

Until converged:

for example(s) sentence i:

- 1. Compute loss I on  $x_i$ I = model( $x_i$ )
- 2. Get gradient  $g_t = l'(x_i)$
- 3. Get scaling factor  $\rho_{t}$
- 4. Set  $\theta_{t+1} = \theta_t \rho_t * g_t$
- 5. Set t += 1

Core idea: Train the model to predict what the next word is via maximum likelihood (equivalently, minimizing crossentropy loss).

# Gradient Descent: Backpropagate the Error

Initialize model

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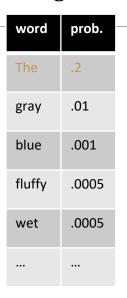
- 1. Compute loss I on  $x_i \leftarrow I = model(x_i)$
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Core idea: Train the model to predict what the next word is via maximum likelihood (equivalently, minimizing crossentropy loss).

This **loss** is the sum of the pertoken cross-entropy loss

44

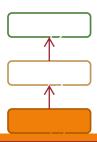
#### log.2



Remember: These probabilities are *computed* as a function of the model parameters!

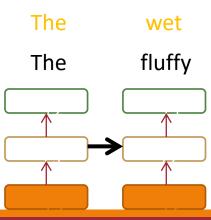
#### The

The



log.2 + log.12

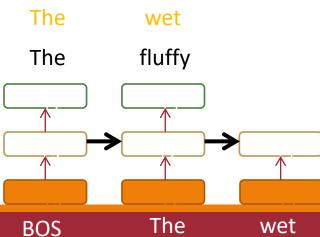
word	prob.	word	prob.
The	.2	black	.2
gray	.01	wet	.12
blue	.001	blue	.001
fluffy	.0005	fluffy	.0005
wet	.0005	gray	.0005



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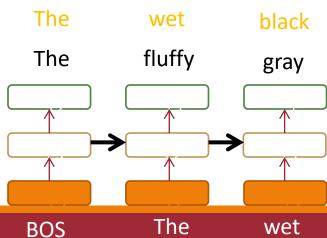


word	prob.	word	prob.
The	.2	black	.2
gray	.01	wet	.12
blue	.001	blue	.001
fluffy	.0005	fluffy	.0005
wet	.0005	gray	.0005



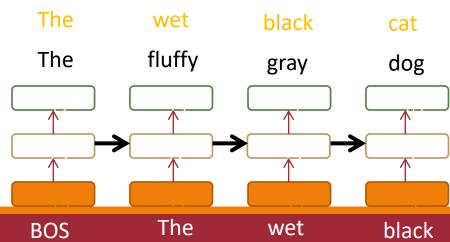
log.2	+	log.12 +	log.2
108.2	-	10g.12 T	105.4

word	prob.	word	prob.	word	prob.
The	.2	black	.2	black	.2
gray	.01	wet	.12	gray	.01
blue	.001	blue	.001	blue	.001
fluffy	.0005	fluffy	.0005	bald	.0005
wet	.0005	gray	.0005	wet	.0005



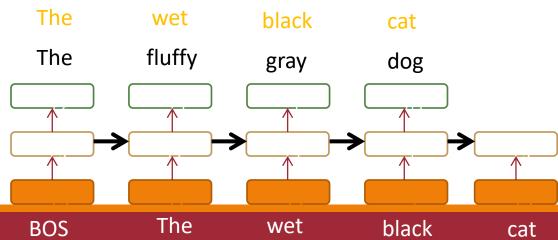


word	prob.	word	prob.	word	prob.	word	prob.
The	.2	black	.2	black	.2	dog	.2
gray	.01	wet	.12	gray	.01	cat	.19
blue	.001	blue	.001	blue	.001	blue	.001
fluffy	.0005	fluffy	.0005	bald	.0005	fluffy	.0005
wet	.0005	gray	.0005	wet	.0005	wet	.0005





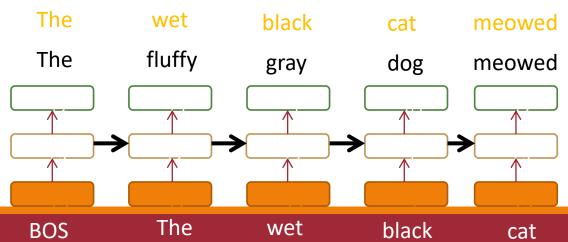
word	prob.	word	prob.	word	prob.	word	prob.
The	.2	black	.2	black	.2	dog	.2
gray	.01	wet	.12	gray	.01	cat	.19
blue	.001	blue	.001	blue	.001	blue	.001
fluffy	.0005	fluffy	.0005	bald	.0005	fluffy	.0005
wet	.0005	gray	.0005	wet	.0005	wet	.0005



50

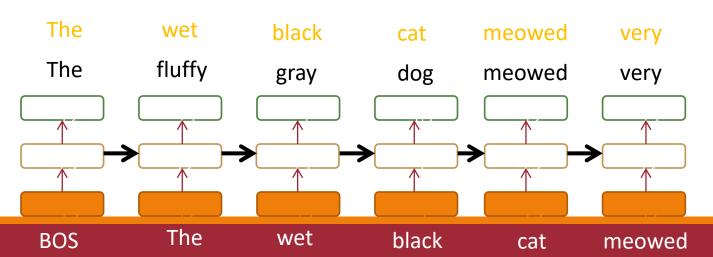
log.2	+	log.12 +	log.2	+	log.19 +	log.3

word	prob.	word	prob.	word	prob.	word	prob.	word	prob
The	.2	black	.2	black	.2	dog	.2	meowed	.3
gray	.01	wet	.12	gray	.01	cat	.19	purred	.2
blue	.001	blue	.001	blue	.001	blue	.001	hissed	.1
fluffy	.0005	fluffy	.0005	bald	.0005	fluffy	.0005	fluffy	.001
wet	.0005	gray	.0005	wet	.0005	wet	.0005	wet	.001
									•••





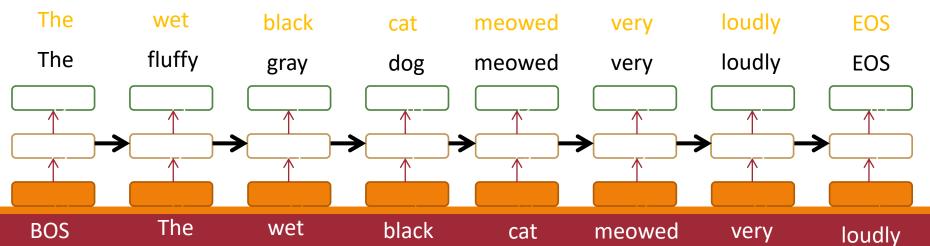
word	prob.	word	prob.	word	prob.	word	prob.	word	prob	word	prob.
The	.2	black	.2	black	.2	dog	.2	meowed	.3	very	.2
gray	.01	wet	.12	gray	.01	cat	.19	purred	.2	lots	.1
blue	.001	blue	.001	blue	.001	blue	.001	hissed	.1	softly	. 1
fluffy	.0005	fluffy	.0005	bald	.0005	fluffy	.0005	fluffy	.001	fluffy	.0005
wet	.0005	gray	.0005	wet	.0005	wet	.0005	wet	.001	wet	.0005
								•••			



(then negate, average)

 $\log .2 + \log .12 + \log .2 + \log .19 + \log .3 + \log .2 + \log .2 + \log .2$ 

word	prob.	word	prob.	word	prob.	word	prob.	word	prob	word	prob.	word	prob	word	prob.
The	.2	black	.2	black	.2	dog	.2	meowed	.3	very	.2	loudly	.2	EOS	.3
gray	.01	wet	.12	gray	.01	cat	.19	purred	.2	lots	.1	softly	.01	and	.1
blue	.001	blue	.001	blue	.001	blue	.001	hissed	.1	softly	. 1	quiet	.001	blue	.001
fluffy	.0005	fluffy	.0005	bald	.0005	fluffy	.0005	fluffy	.001	fluffy	.0005	fluffy	.001	fluffy	.0005
wet	.0005	gray	.0005	wet	.0005	wet	.0005	wet	.001	wet	.0005	wet	.001	wet	.0005



# Gradient Descent: Backpropagate the Error

Initialize model

Set t = 0

Pick a starting value  $\theta_t$ 

Until converged:

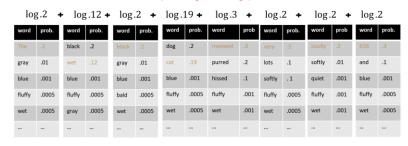
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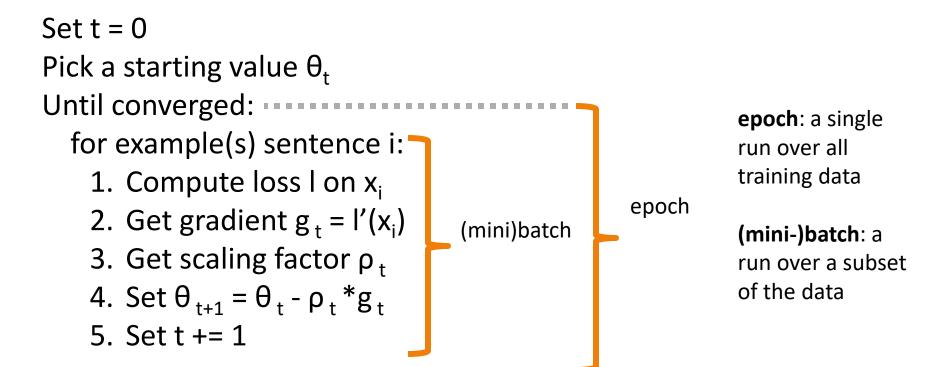
Core idea: Train the model to predict what the next word is via maximum likelihood (equivalently, minimizing crossentropy loss).

This **loss** is the sum of the pertoken cross-entropy loss

(then negate, average)



# Gradient Descent: Backpropagate the Error



### Flavors of Gradient Descent

#### "Online"

#### Set t = 0Pick a starting value $\theta_t$ Until converged:

for example i in full data:

- 1. Compute loss I on x<sub>i</sub>
- 2. Get gradient  $g_t = l'(x_i)$
- 3. Get scaling factor  $\rho_+$
- 4. Set  $\theta_{t+1} = \theta_t \rho_t * g_t$
- 5. Set t += 1

done

#### "Minibatch"

Set t = 0

Pick a starting value 
$$\theta_t$$

Until converged:

get batch  $B \subset full$  data

set  $g_t = 0$ 

for example(s) i in B:

1. Compute loss I on  $x_i$ 

2. Accumulate gradient

 $g_t += l'(x_i)$ 

done

Get scaling factor  $\rho_t$ 

Set  $\theta_{t+1} = \theta_t - \rho_t * g_t$ 

Set t += 1

#### "Batch"

```
Set t = 0
Pick a starting value \theta_{+}
Until converged:
  set g_t = 0
  for example(s) i in full data:
      1. Compute loss I on x<sub>i</sub>
      2. Accumulate gradient
           g_{+} += I'(x_{i})
   done
  Get scaling factor ρ<sub>+</sub>
  Set \theta_{t+1} = \theta_t - \rho_t * g_t
  Set t += 1
```

## Why Is Training RNNs Hard?

Conceptually, it can get strange

But really getting the gradient just requires many applications of the chain rule for derivatives

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Vanishing gradients

Multiply the *same* matrices at *each* timestep → multiply *many* matrices in the gradients

## Why Is Training RNNs Hard?

Conceptually, it can get strange

But really getting the gradient just requires many applications of the chain rule for derivatives

Vanishing gradients

Multiply the *same* matrices at *each* timestep → multiply *many* matrices in the gradients

One solution: clip the gradients to a max value