UNINFORMED SEARCH

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> 9/12/2023 CMSC 671

By the end of class today, you will be able to:

- 1. Choose when to use breadth-first, depth-first, or uniform-cost search for a given problem
- 2. Assess the limitation of uninformed search

Modified from slides by Dr. Cassandra Kent

HW 1 RELEASED

Pac-Man search Due 9/26 at 11:59pm https://laramartin.net/Principles-of-AI/homeworks/search/search.html



What does it mean for an agent to have a "model"?

RECAP

Components of a Search Problem

- Actions
- States
- Initial state
- Transition model
- Goal test
 - Step cost



What's the difference between DFS and BFS?

9/12/2023 - Uninformed Search

EVALUATING SEARCH ALGORITHMS

WHY HAVE DIFFERENT WAYS TO TRAVERSE A TREE?

We can look at four criteria:

- Completeness
- Optimality
- Time complexity
- Space complexity

COMPLETENESS

Completeness: Will the algorithm always find a solution? Example problem: Brute-force simple password guessing agent

- States: all combinations of letters a-z
- Initial state: empty string
- Actions: add a letter a-z
- Transition model: append letter to end of password
- Goal test: type in password and see if it works

BFS VS DFS: COMPLETENESS

Completeness: Will the algorithm always find a solution? Example problem: Brute-force simple password guessing agent

Breadth-First Search

. . .

- States expanded: a, b, c, ..., aa, ab, ac, ..., ba, bb, bc, ..., ca, cb,
- Is complete (given infinite time)

DFS can not handle state spaces with infinite depth!

- Is not complete

BFS VS DFS: OPTIMALITY

Optimality: Will the algorithm always find the best (shortest) path to the goal?

Breadth-First Search

- Fully expands all nodes at minimum depth before continuing
- Is optimal

- Counter example: http://graphonline.ru/en/?graph =rOFlnolAZkfZXorA
- Is not optimal

BFS VS DFS: TIME COMPLEXITY

Time complexity: How long does it take to find a solution? Depends on:

- Branching factor *b*: the number of actions the agent can take at any state
- Depth of solution *d*: the optimal solution length
- Maximum depth of tree *m*

Breadth-First Search

- $O(b^d)$
- Must search all branches until solution depth is reached

- $O(b^m)$
- Must search to the end of the tree

BFS VS DFS: <u>SPACE</u> COMPLEXITY

Space complexity: How much memory does it take to execute? Depends on:

- Branching factor *b*: the number of actions the agent can take at any state
- Depth of solution *d*: the optimal solution length
- Maximum depth of tree *m*

Breadth-First Search

- $O(b^d)$
- Must hold full row of search tree in memory

- O(bm)
- Holds 1 set of successors at each row of search tree in memory

BFS VS DFS

Why would we ever use DFS?

Breadth-First Search

- Complete
- Optimal
- $O(b^d)$ time complexity
- $O(b^d)$ space complexity

Depth-First Search

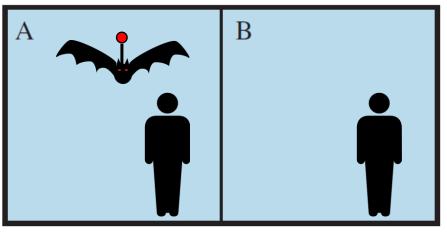
- Not complete
- Not optimal
- $O(b^m)$ time complexity
- O(bm) space complexity

BFS can be **physically impossible to run** for large search depths and branching factors!

Will using search algorithms for our agent functions produce <u>rational</u> behavior?

BACK TO VAMPIRE WORLD

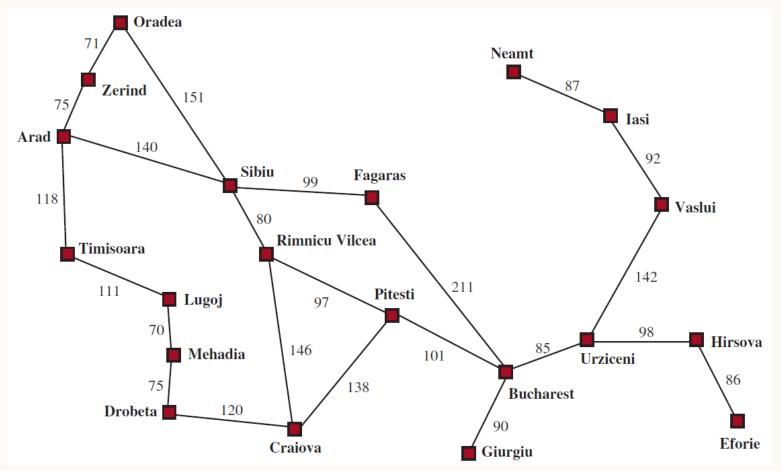
Agent: Vampire Performance measure: Suck as much blood over time as possible Environment: Location, humans Actuators: Flying, sucking Sensors: Short-range sonar (human detection)



if [A, Empty]: return Right
if [B, Empty]: return Left
if [A or B, Human]: return Suck
Is this a rational (vampire) agent?

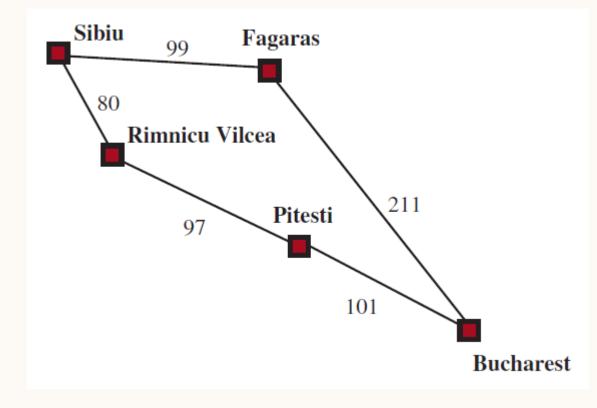
Will using search algorithms for our agent functions produce <u>rational</u> behavior?

- BFS + DFS performance measure: number of actions taken
- What about other measures?



Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest

- BFS is no longer optimal
- Need to account for step cost
- Use Uniform-Cost Search



function TREE-SEARCH(*problem*) **returns** a solution, or failure initialize the frontier using the initial state of *problem*

loop do

if the frontier is empty then return failure

choose a leaf node and remove it from the frontier

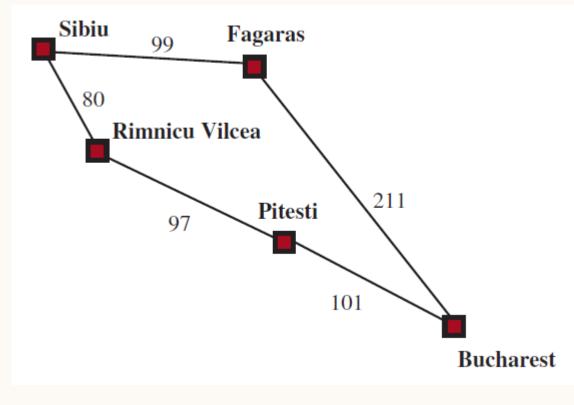
if the node contains a goal state **then return** the corresponding solution expand the chosen node, adding the resulting nodes to the frontier

Store frontier as a priority queue, prioritized by path cost g(n)

• Path cost calculated as accumulation of step costs from initial state to each node

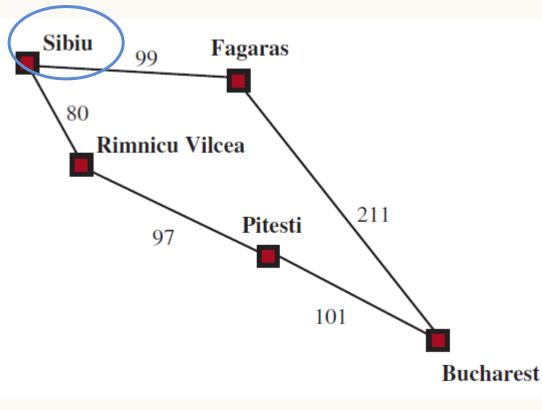
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [Sibiu (0)]

Current node: *none*



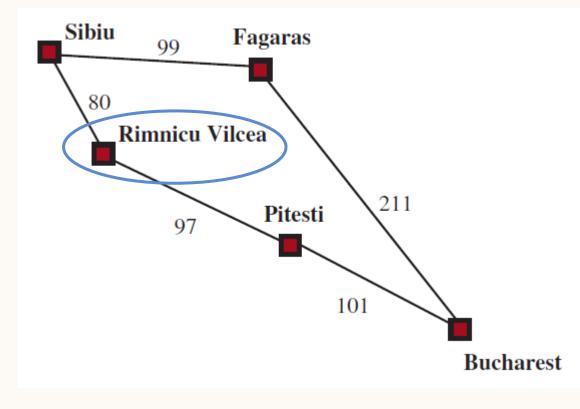
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [R.V. (80), F. (99)]

Current node: Sibiu (0)



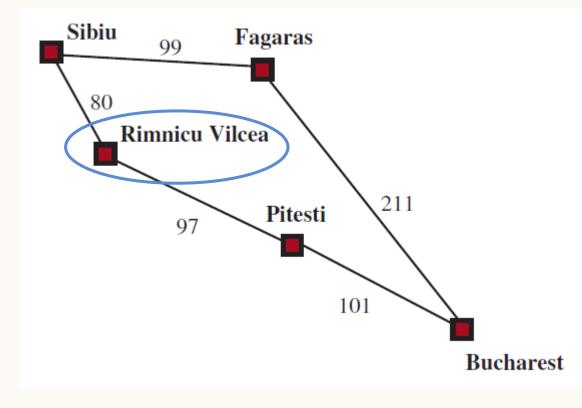
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [F. (99)]

Current node: R.V. (80)



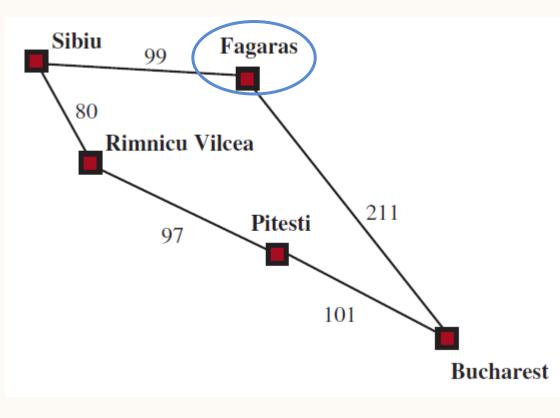
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [F. (99), P. (80+97=177)]

Current node: R.V. (80)



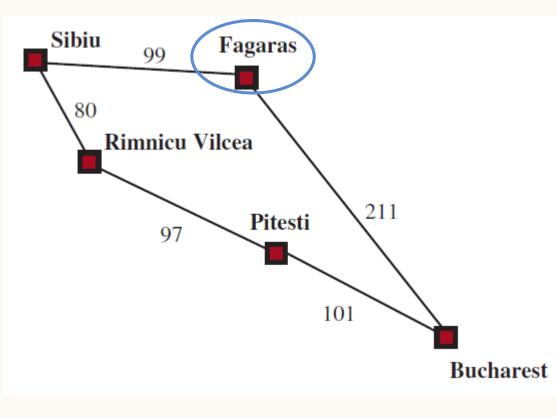
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [P. (177)]

Current node: F. (99)



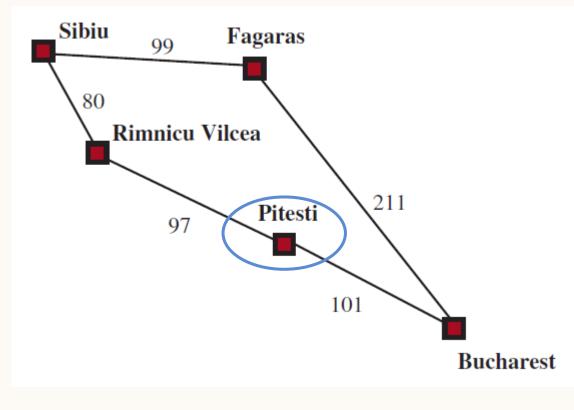
Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier: [P. (177), B. (99+211=310)]

Current node: F. (99)



Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest
Frontier:
[B. (310)]

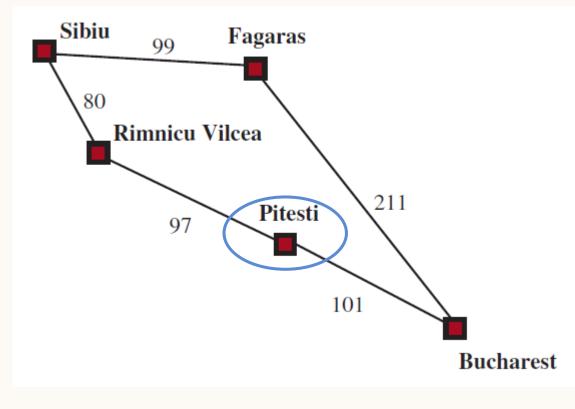
Current node: P. (177)



Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier:

[B. (177+101=278), B. (310)]

Current node: P. (177)

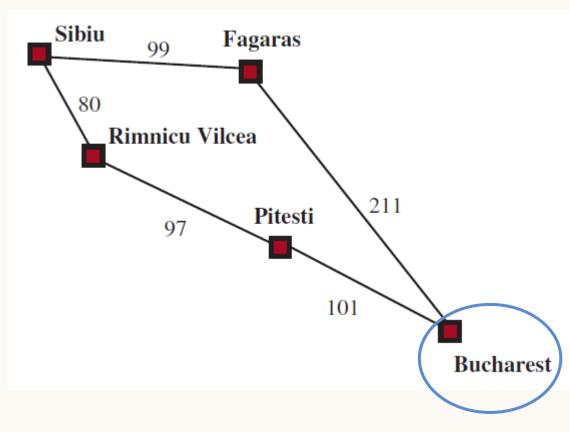


Problem: find the shortest (in terms of distance) path from Sibiu to Bucharest Frontier:

[]

Current node: B. (278)

Return: [Sibiu, Rimnicu Vlicea, Pitesti, Bucharest]



PROPERTIES OF UCS (VS BFS)

Uniform-Cost Search

- Complete
- Optimal
- $O(b^{1+C^*/\epsilon})$ time complexity
- $O(b^{1+C^*/\epsilon})$ space complexity

Breadth-First Search

- Complete
- Optimal
- $O(b^d)$ time complexity
- $O(b^d)$ space complexity

where C^* is the optimal path cost to the goal, and ϵ is the minimum step cost (must be positive)

IN GROUPS: WHEN WOULD YOU USE THEM?

Depth-First Search

Breadth-First Search Unified-Cost Search

- Mazes
- Simple robot path (limited memory)
- Finding wreck in ocean (branching factor too high)
- Social network (finding how a friend is connected)

- Find closest destination
- Finding people within an organization (e.g., LinkedIn)
- Web crawler

- Shortest path (distance)/map directions
- Internet packet sending (fastest network)
- Finding cheapest flight w/ layovers

BACK TO BFS VS DFS

Breadth-First Search

- Complete
- Optimal
- $O(b^d)$ time complexity
- $O(b^d)$ space complexity

Depth-First Search

- Not complete
- Not optimal
- $O(b^m)$ time complexity
- O(bm) space complexity

We have a complete, optimal algorithm that may be impossible to run, and a bad algorithm that's very memory efficient...

Can we get the benefits of both?



DFS AND THE PROBLEM OF INFINITE DEPTH

Problem: Brute-force simple password guessing agent

- States: all combinations of letters a-z
- Initial state: empty string
- Actions: add a letter a-z
- Transition model: append letter to end of password
- Goal test: type in password and see if it works

- At a certain depth, it doesn't make sense to expand states
 - (probably no one will have a password with 1,000 characters? 10,000? ∞ ?)

DEPTH-LIMITED SEARCH

- Set a reasonable depth limit for the search problem
- Run depth-first search as normal, but do **not** add successor nodes to the frontier if the current node is at the depth limit

DEPTH-LIMITED SEARCH

Problem: Brute-force simple password guessing agent Depth-First Search

- **Depth-Limited Search**
- For a depth limit of 4:
- - Eventually will generate all strings of length <= 4!

PROPERTIES OF DEPTH-LIMITED SEARCH

- Is depth-limited search complete?
- Is depth-limited search optimal?

Take a couple minutes and try to figure out under what conditions depth-limited search is complete or optimal.

Some terms that may help: b: branching factor l: depth limit

d: depth of the goal *m*: maximum depth of tree

FOR NEXT CLASS

- Start reading Chapter 3.5-3.7
- If you have Module 1/Search for your paper presentation, start looking for a paper and send it to me & Aydin
 - Presentation on Thursday Sept 21