



Controllable Neural Plot Generation via Reward Shaping

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*Equal contribution

Why Storytelling?



Automated Storytelling



Stories can...

- Help us plan
- Teach us
- Train us for hypothetical scenarios
- Do anything else that requires long-term context and commonsense information!

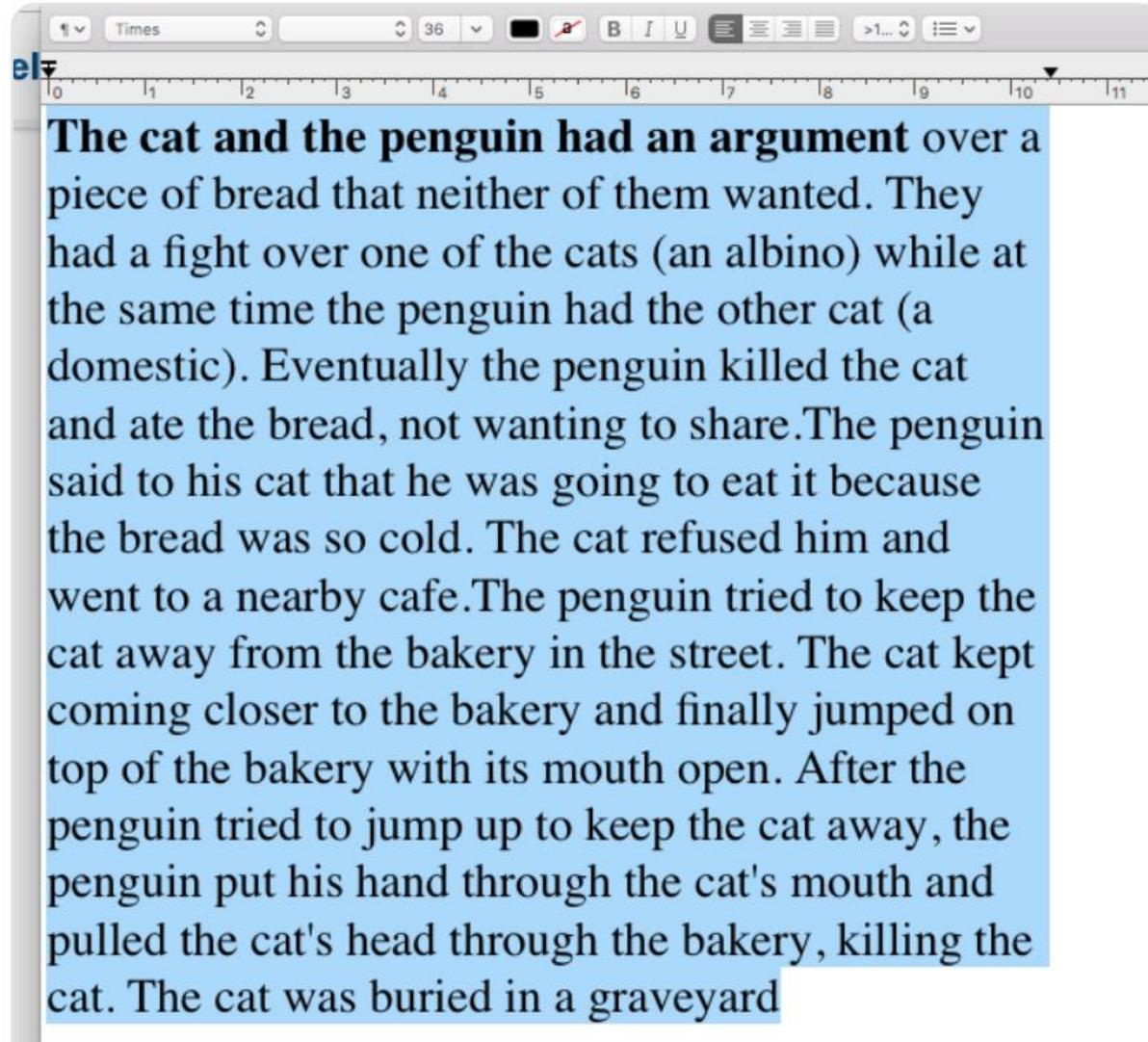


will knight

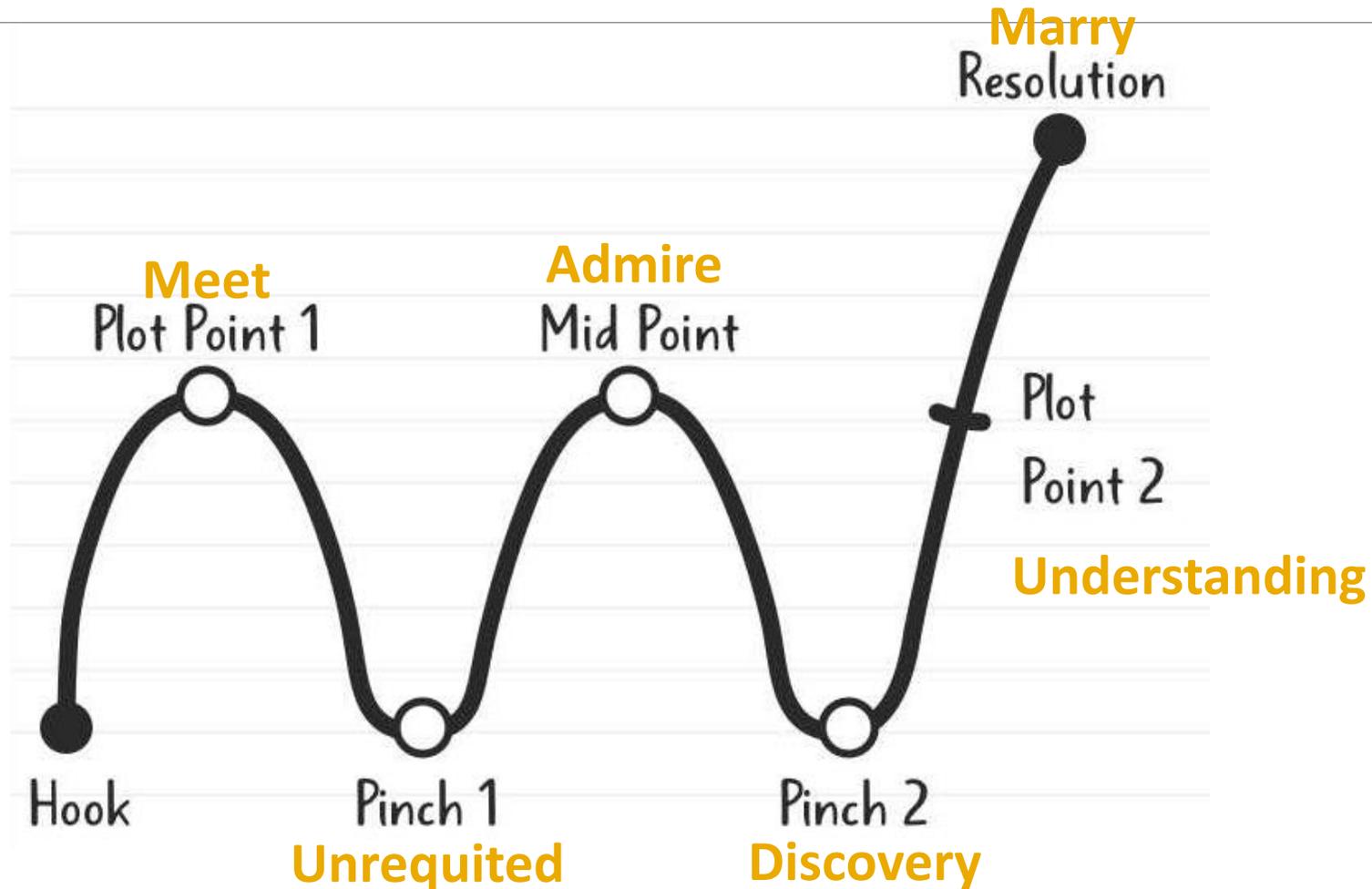
@willknight

Follow

Here's a short story i generated using OpenAI's GPT-2 tool (prompt in bold)



Plot Generation



How can we make
controllable neural
storytellers?

Controllable Story Generation

We need a criteria for success → Reach a “goal verb”

- Given any start of the story, we want it to end a certain way
- E.g. “I want a story where...”
 - The bad guys *lose*.
 - The couple *marries*.

What we did:

We use reinforcement learning with **reward shaping** to create a storytelling system that can **incrementally** head toward a plot goal

Outline

1. The problem: generating a sequence of plot points
2. Reinforcement learning storytelling
3. Our reward shaping technique
4. Automated evaluation
5. Human evaluation

Event/Sentence Generation

Simonetta learns of Tito's affections for her.



She loved Tito before she loved Luigi.



Sentence Sparsity

Simonetta learns of Tito's affections for her.

Problem: Sentences like this only appear once in the dataset

Solution: Fixing sparsity by separating semantics (meaning) from syntax (grammar)

Event Representation

⟨subject, verb, direct object, modifier⟩

Original sentence: simonetta learns of tito s affections for her

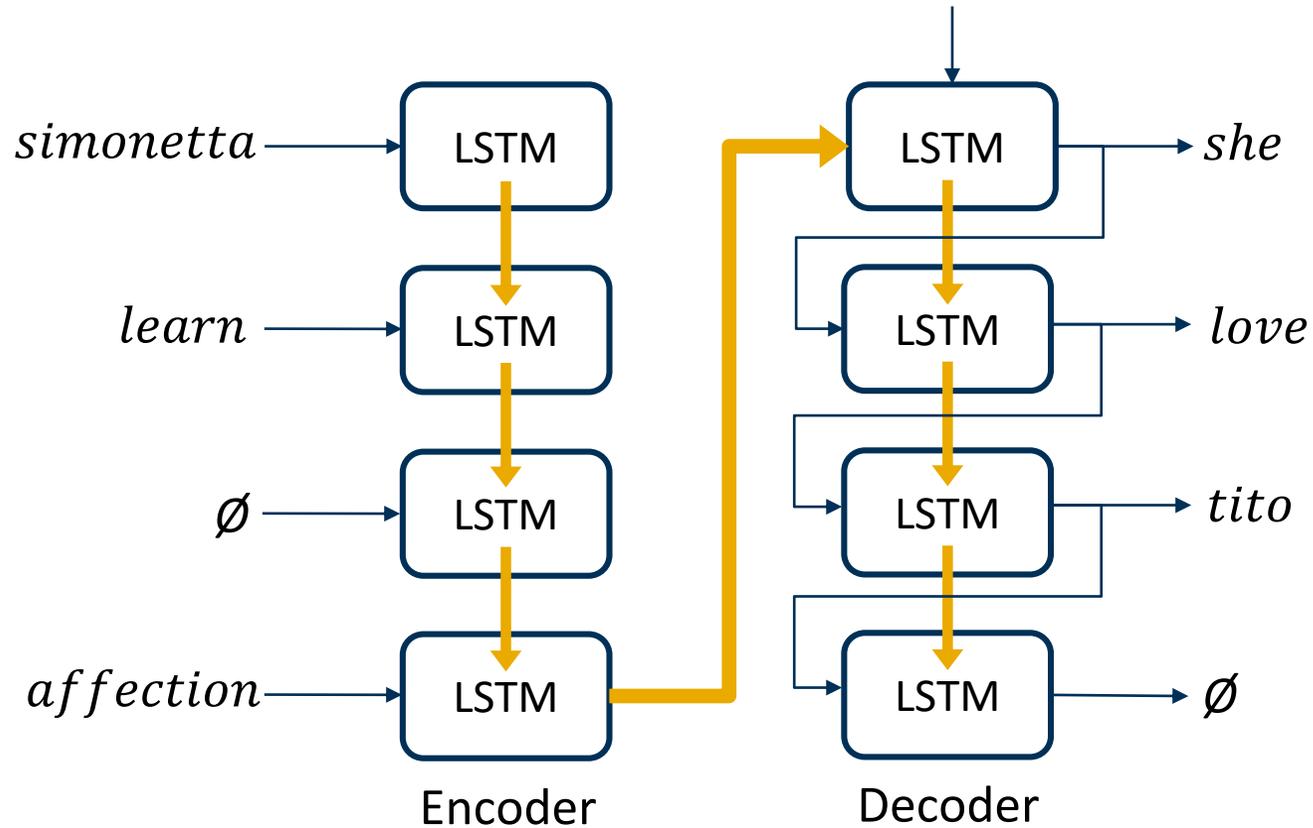
Event: ⟨simonetta, learn, ∅, affection⟩

Generalized Event: ⟨⟨PERSON⟩0, learn-14-1, ∅, state.n.02⟩

Martin, L. J., Ammanabrolu, P., Wang, X., Hancock, W., Singh, S., Harrison, B., & Riedl, M. O. (2018). Event Representations for Automated Story Generation with Deep Neural Nets. In *AAAI* (pp. 868–875).

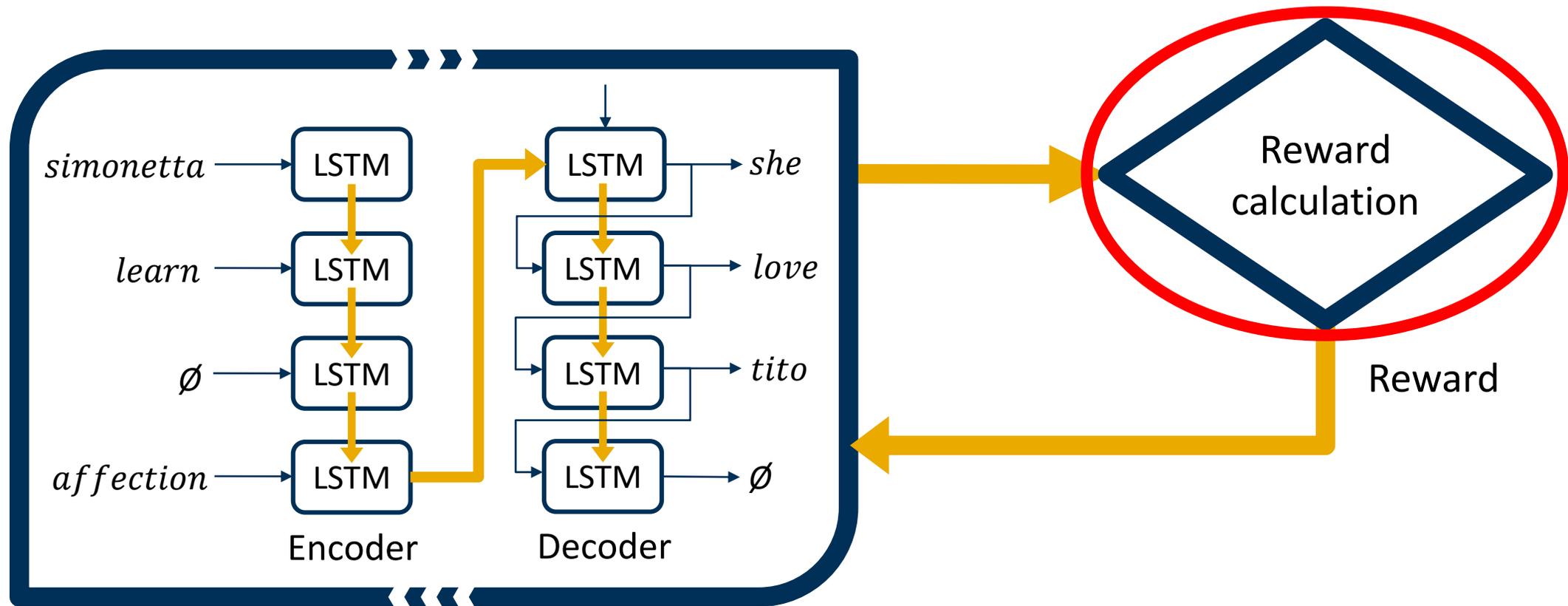


Sequence-to-Sequence Refresher

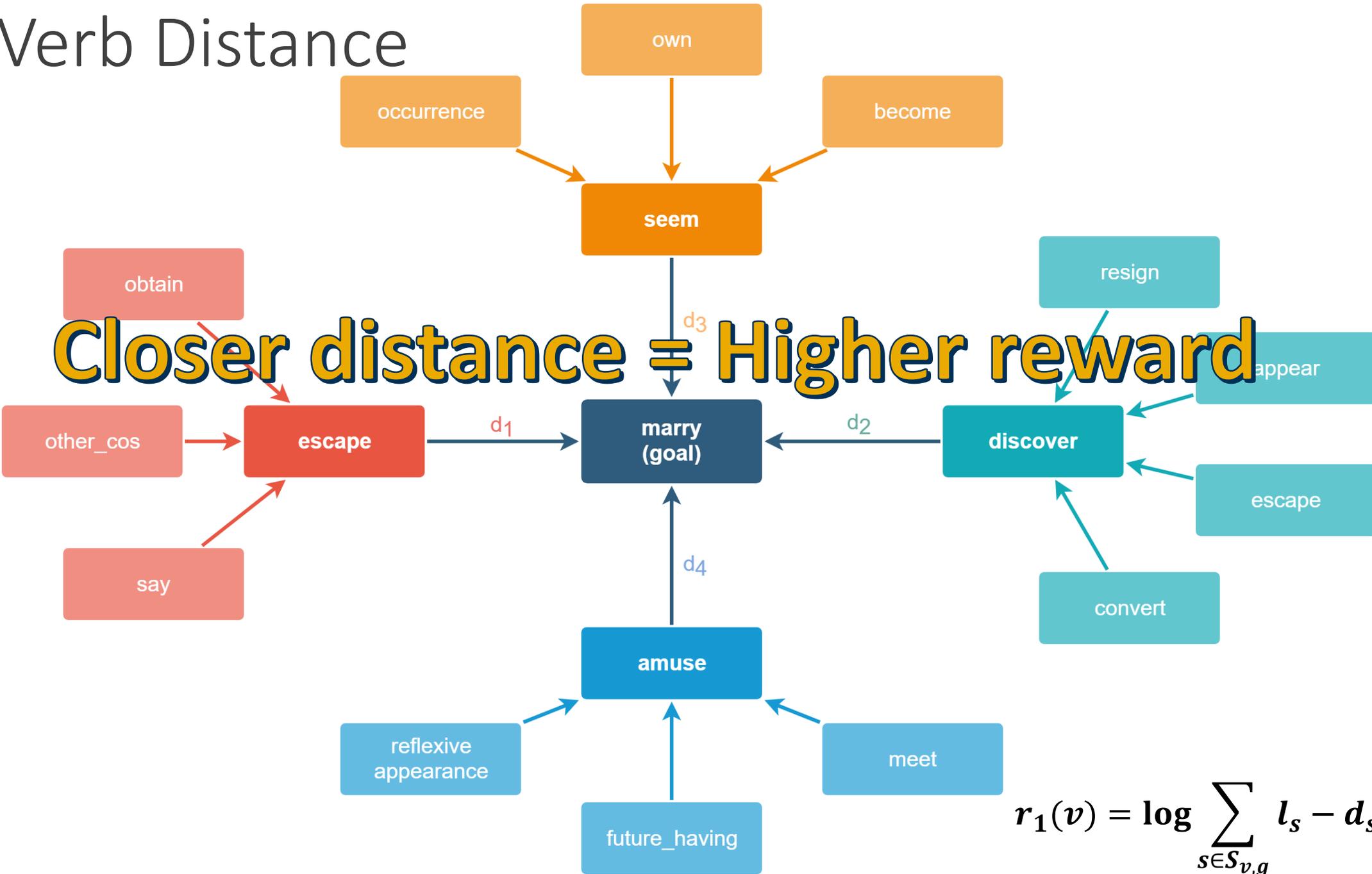


Sutskever, I., Vinyals, O., & Le, Q. V. (2014). Sequence to Sequence Learning with Neural Networks. In *Advances in Neural Information Processing Systems* (pp. 3104–3112).

REINFORCE (Seq2Seq++)



#1 Verb Distance



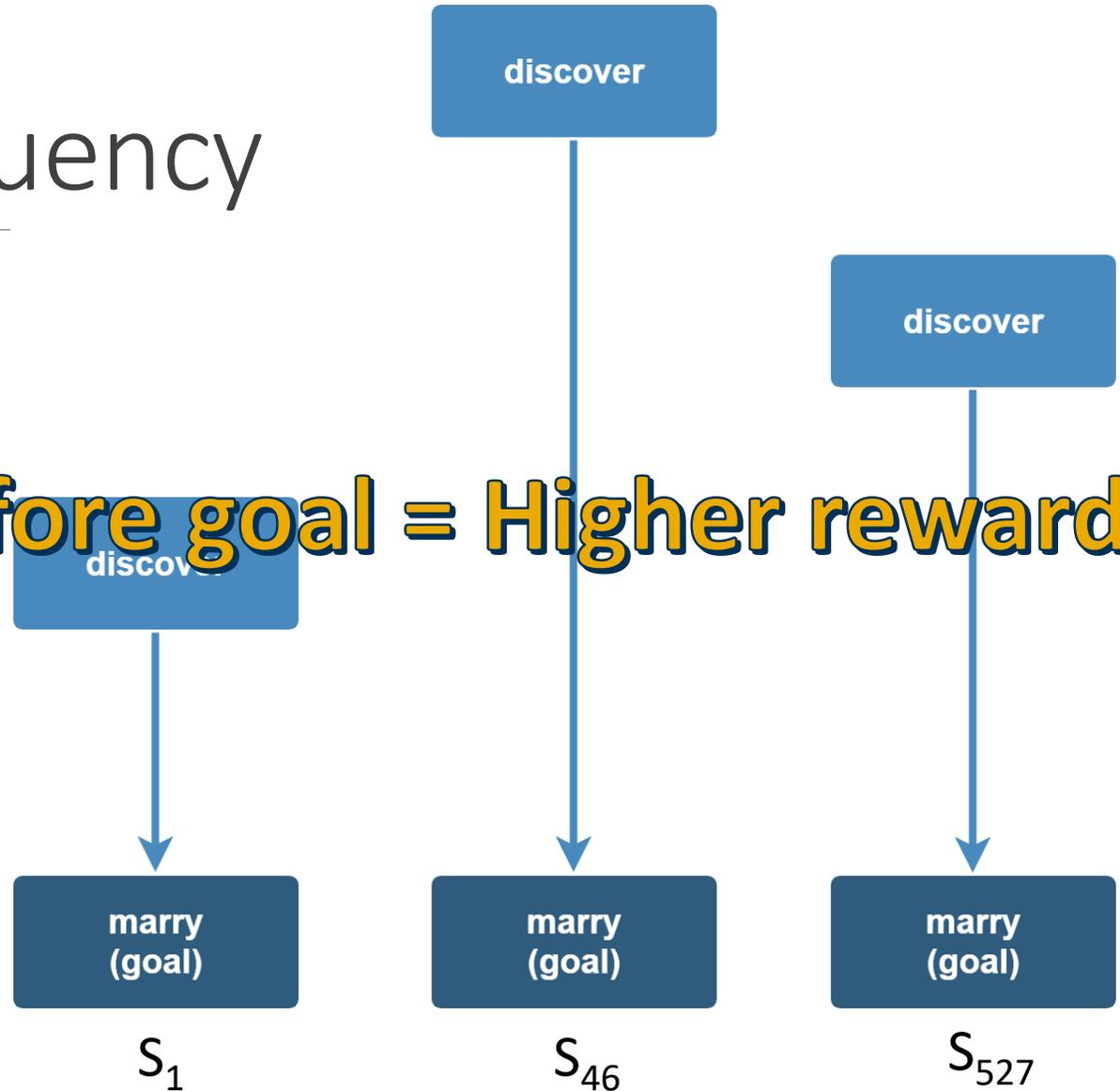
Closer distance = Higher reward

$$r_1(v) = \log \sum_{s \in \mathcal{S}_{v,g}} l_s - d_s(v, g)$$

#2 Story-Verb Frequency

$$r_2(v) = \log \frac{k_{v,g}}{N_v}$$

Appear frequently before goal = Higher reward



Final Reward Equation

Affects step size for backprop

$$R(v) = \alpha \times r_1(v) \times r_2(v)$$

Verb Distance to Goal

Story-Verb Frequency

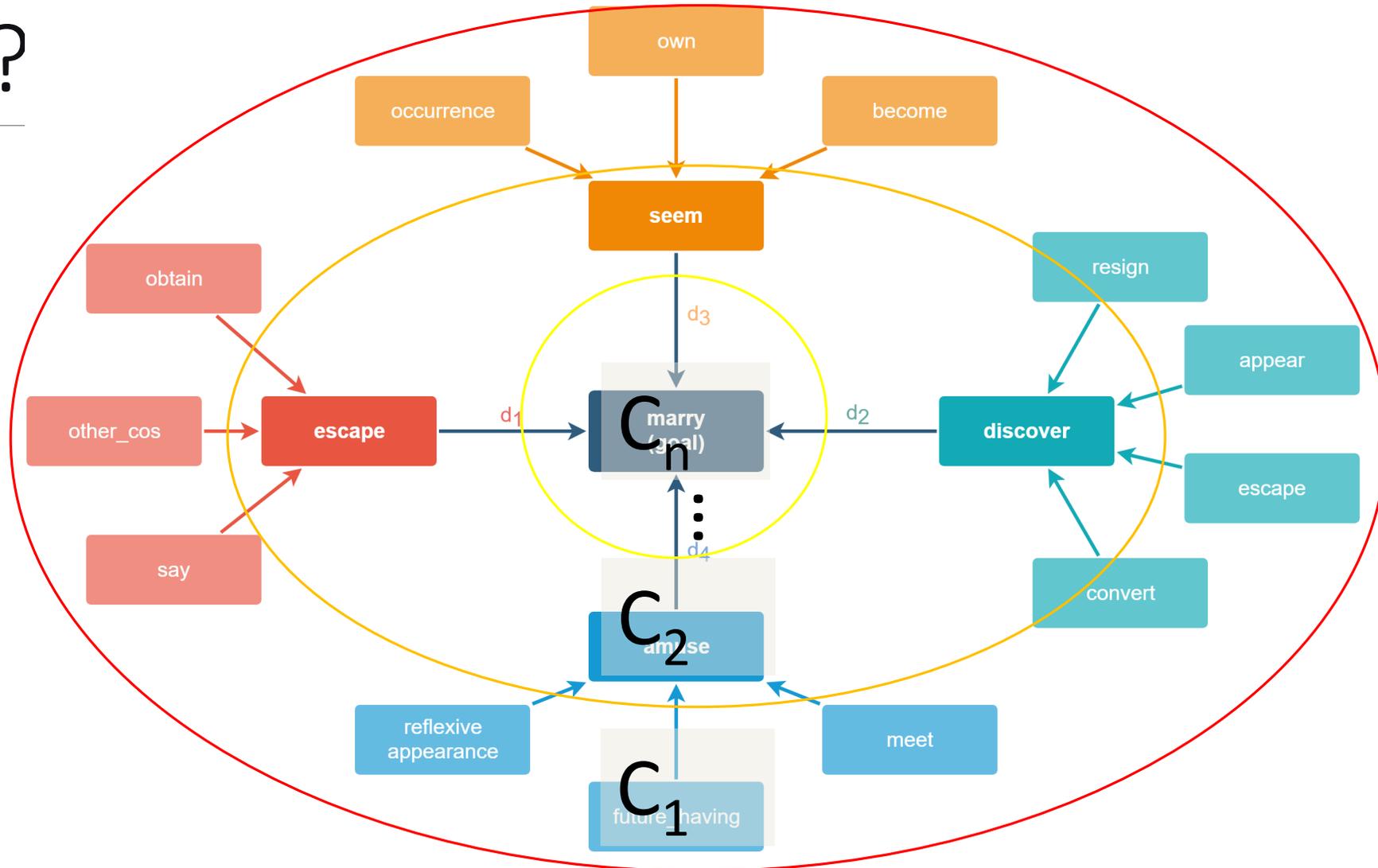
Results

Goal	Model	Average Story Length	Average Perplexity	Goal Achievement Rate
admire	Seq2Seq	7.11	48.06	35.52%
	REINFORCE	7.32	5.73	15.82%
marry	Seq2Seq	6.94	48.06	39.92%
	REINFORCE	7.38	9.78	24.05%

What now?

Cluster based
on reward score

Constrain
system to
sample from
next cluster

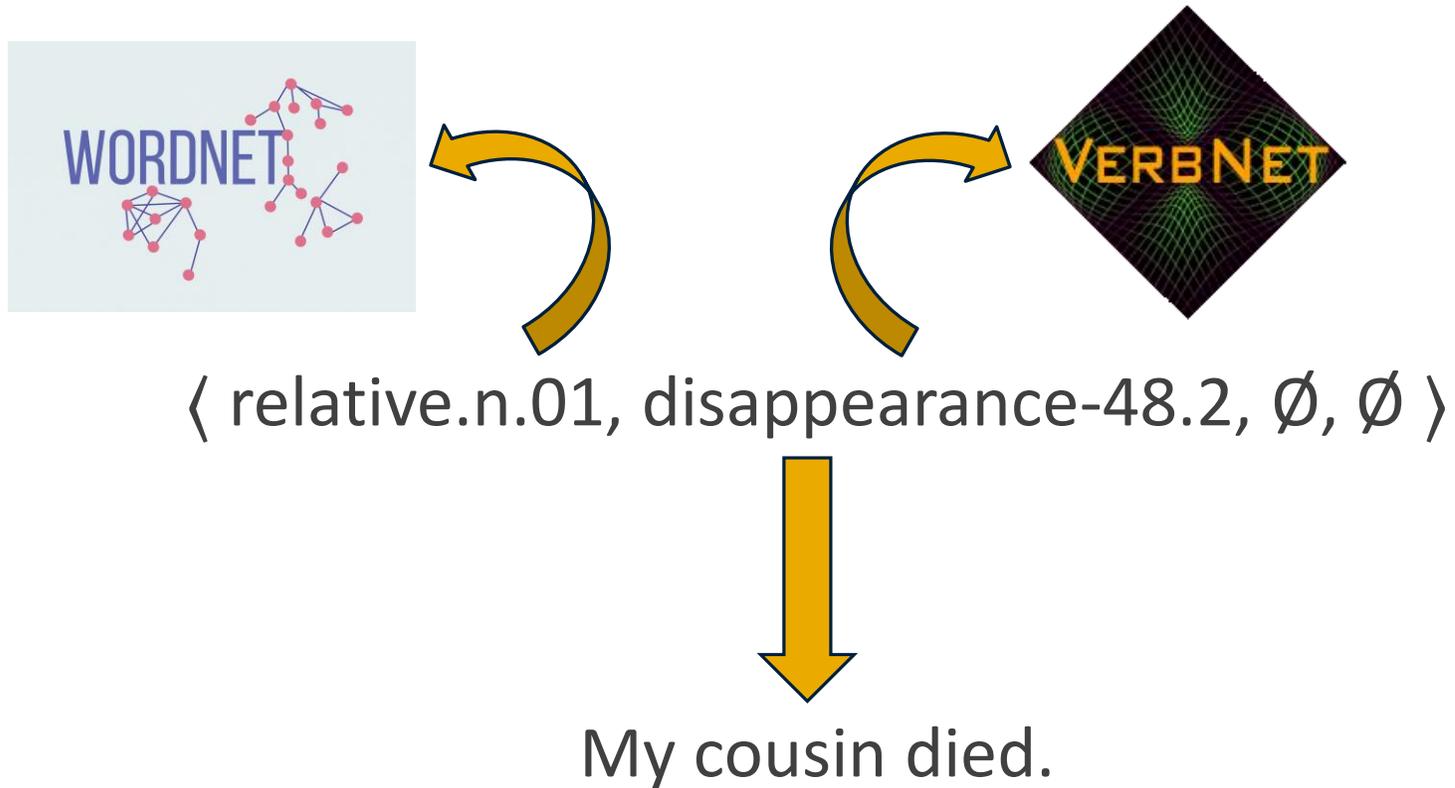


Results

Goal	Model	Average Story Length	Average Perplexity	Goal Achievement Rate
admire	Seq2Seq	7.11	48.06	35.52%
	REINFORCE	7.32	5.73	15.82%
	REINFORCE + Clustering	4.90	7.61	94.29%
marry	Seq2Seq	6.94	48.06	39.92%
	REINFORCE	7.38	9.78	24.05%
	REINFORCE + Clustering	5.76	7.05	93.35%

But are the stories
actually any *good*?

Event Translation via Humans



Example (Goal: hate/admire)

DRL Event Output ⟨ subject, verb, object, modifier ⟩	Translated Sentence
⟨ relative.n.01, disappearance-48.2, ∅, ∅ ⟩	My cousin died.
⟨ NE1, say-37.7-1, visit, ∅ ⟩	Alexander insisted on a visit.
⟨ NE1, meet-36.3-1, female.n.02, ∅ ⟩	Alexander met her.
⟨ NE0, correspond-36.1, ∅, NE1 ⟩	Barbara commiserated with Alexander.
⟨ physical_entity.n.01, marry-36.2, ∅, ∅ ⟩	They hugged.
⟨ group.n.01, contribute-13.2-2, ∅, LOCATION ⟩	The gathering dispersed to Hawaii.
⟨ gathering.n.01, characterize-29.2-1-1, time_interval.n.01, ∅ ⟩	The community remembered their trip.
⟨ physical_entity.n.01, cheat-10.6, pack, ∅ ⟩	They robbed the pack.
⟨ physical_entity.n.01, admire-31.2, social_gathering.n.01, ∅ ⟩	They adored the party.

Human Evaluation Methods

175 Mechanical Turkers rated statements on a 5-point Likert scale

For each of 3 conditions:

- REINFORCE + Clustering (Ours)
- Baseline Seq2Seq
- Testing Set Stories (Translated Events; Gold Standard)

Questionnaire

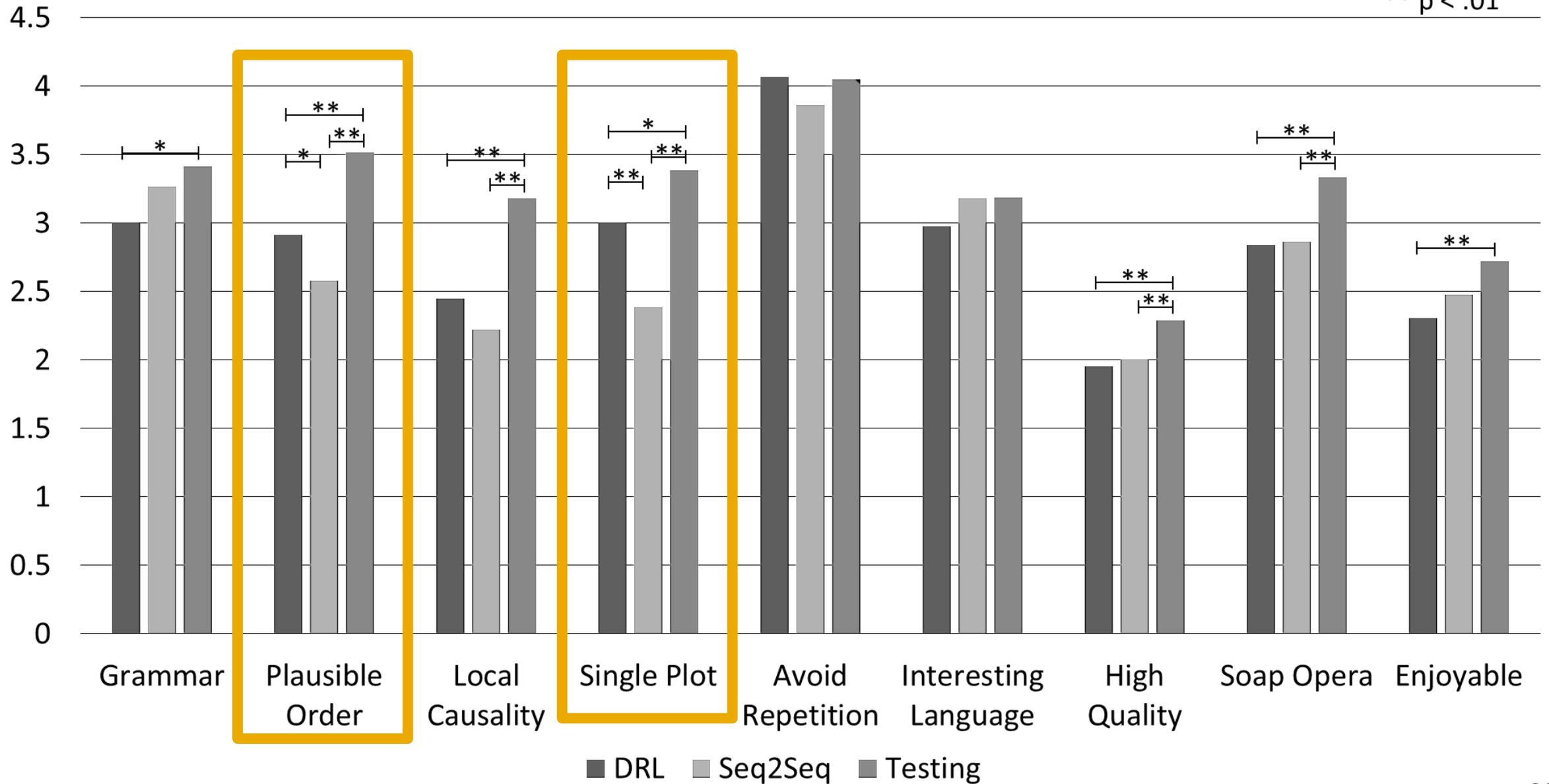
1. ~~This story exhibits CORRECT GRAMMAR.~~
2. This story's events occur in a PLAUSIBLE ORDER.
3. This story's sentences MAKE SENSE given sentences before and after them.
4. This story FOLLOWS A SINGLE PLOT.
5. This story AVOIDS REPETITION.
6. ~~This story uses INTERESTING LANGUAGE.~~
7. This story is of HIGH QUALITY.
8. This story REMINDS ME OF A SOAP OPERA.
9. This story is ENJOYABLE.

Purdy, C., Wang, X., He, L., & Riedl, M. (2018). Towards Predicting Generated Story Quality with Quantitative Metrics. In *14th AAI Conference on Artificial Intelligence and Interactive Digital Entertainment (AIIDE '18)*.



Average Score per Model

* p < .05
** p < .01



In Conclusion...

- Most neural storytelling methods lack “controllability”
- We used reinforcement learning to guide the story toward a goal (verb)
- Reward shaping and clustering → logical plot progression
- RL plots resulted in stories with more of a “single plot” and “plausible ordering” than Seq2Seq baseline



Thank you!

Read the paper on arXiv!
<https://arxiv.org/abs/1809.10736>

QUESTIONS?

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